The background features a dark blue gradient with intricate white and light blue technical diagrams. These include concentric circles, dashed lines, and circular scales with numerical markings (e.g., 40, 150, 160, 170, 180, 190, 200, 210, 220, 230, 240, 250, 260). Some circles have arrows pointing inwards or outwards, suggesting a process or measurement cycle.

# INTERCOMPARISON OF THE ESA SENTINEL-5P NO<sub>2</sub> TROPOSPHERIC COLUMN NUMBER DENSITY PRODUCT AGAINST IN-SITU GROUND MEASUREMENTS

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UNIVERSITY OF WARSAW

DR JAN MUSIAŁ, CLOUDFERRO

# PHD RESEARCH TOPIC AND HYPOTHESIS

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PhD  
research  
topic:

Potential of using Sentinel-5P satellite data to support air pollution monitoring in Poland, using computing cloud

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Hypothesis:

Sentinel-5P (S-5P) satellite data combined with meteorological data can be used to support the air quality monitoring system in Poland

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# MOTIVATION

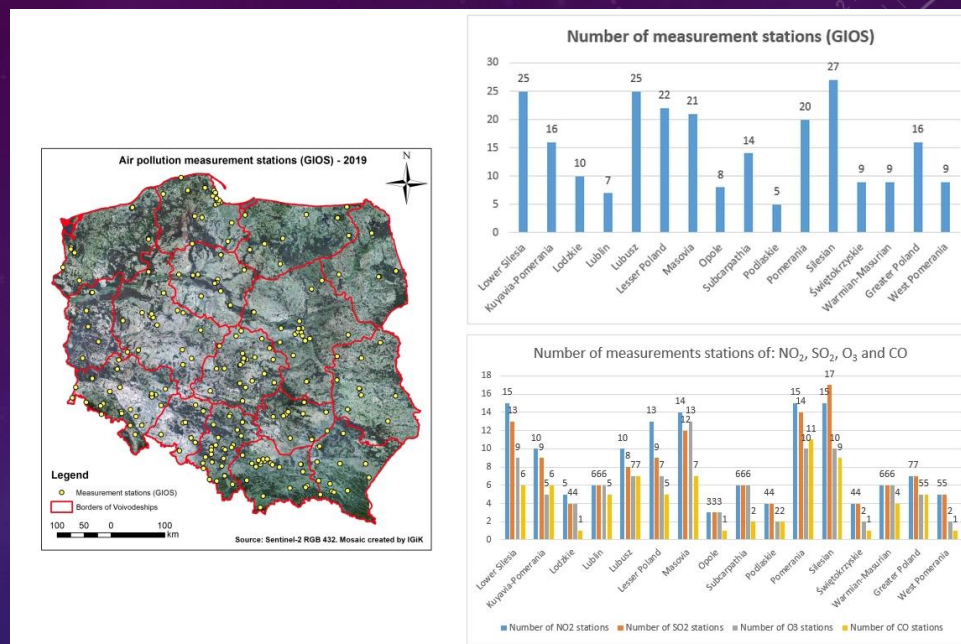
Mission has started in October 2017

Data has been provided from July 2018

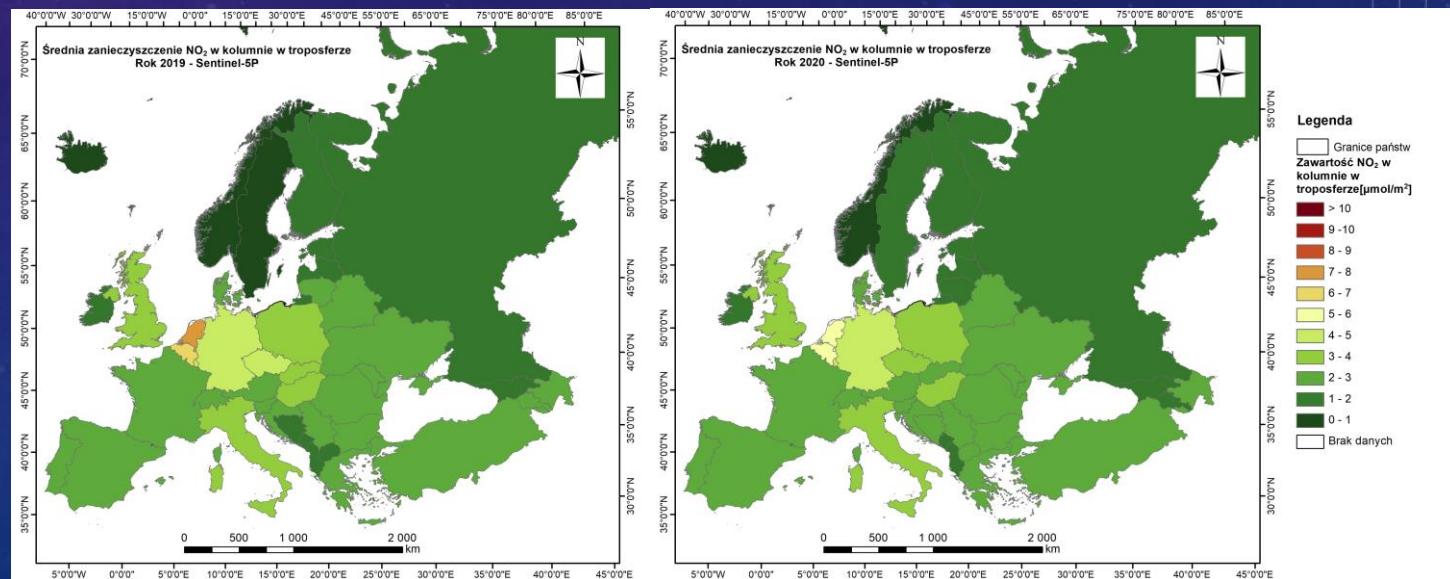
Spatial data

Supplementing monitoring with data from non-urban regions

Poor air quality over Poland



National system of air quality monitoring in Poland.



NO<sub>2</sub> TVCD over Europe – average NO<sub>2</sub> level in 2019 (left) and 2020 (right)

# SENTINEL-5P PRECURSOR

Sentinel-5P

Passive sensor

Start mission

- 13th of October 2017

Temporal resolution – 1 day (at the same point in every 17 days)

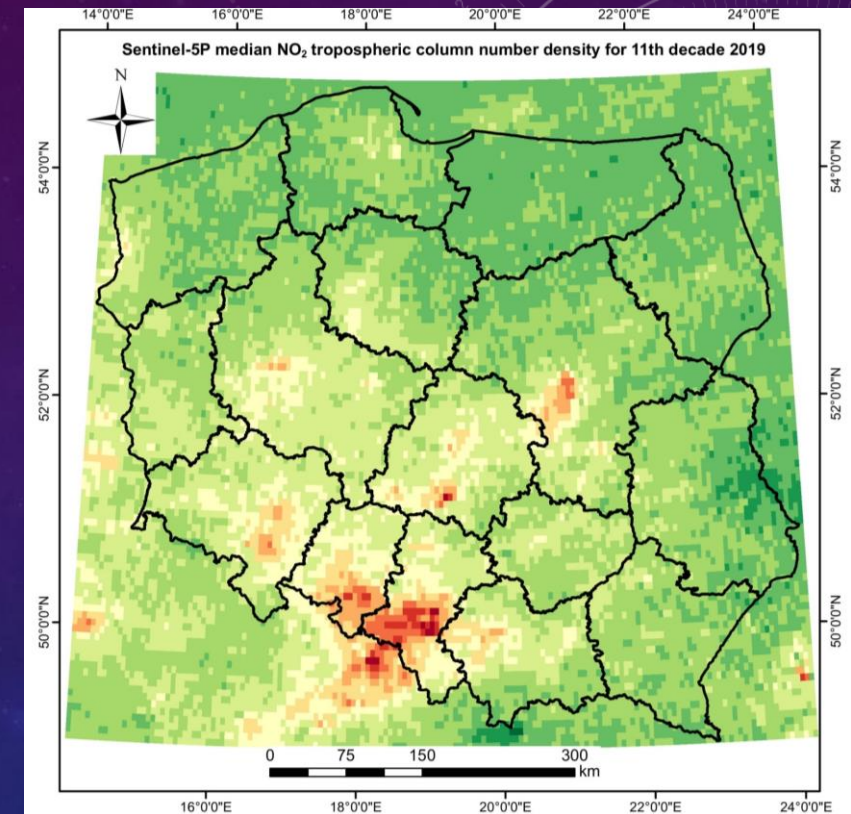
Spatial resolution – 3,5kmx7km, 7kmx7km (od sierpnia 2020 – 3,5kmx5,5km)

Sensor: TROPOMI

Objectives

- Monitoring of the atmosphere and air pollution

	UV		UVIS		NIR		SWIR	
Band	1	2	3	4	5	6	7	8
Range [nm]	270-300	300-320	320-405	405-465	675-725	725-775	2305-2345	2345-2385



Products Nitrogen dioxide

Sulphur dioxide

Carbon monoxide

Methane

Aerosols

Formaldehydes

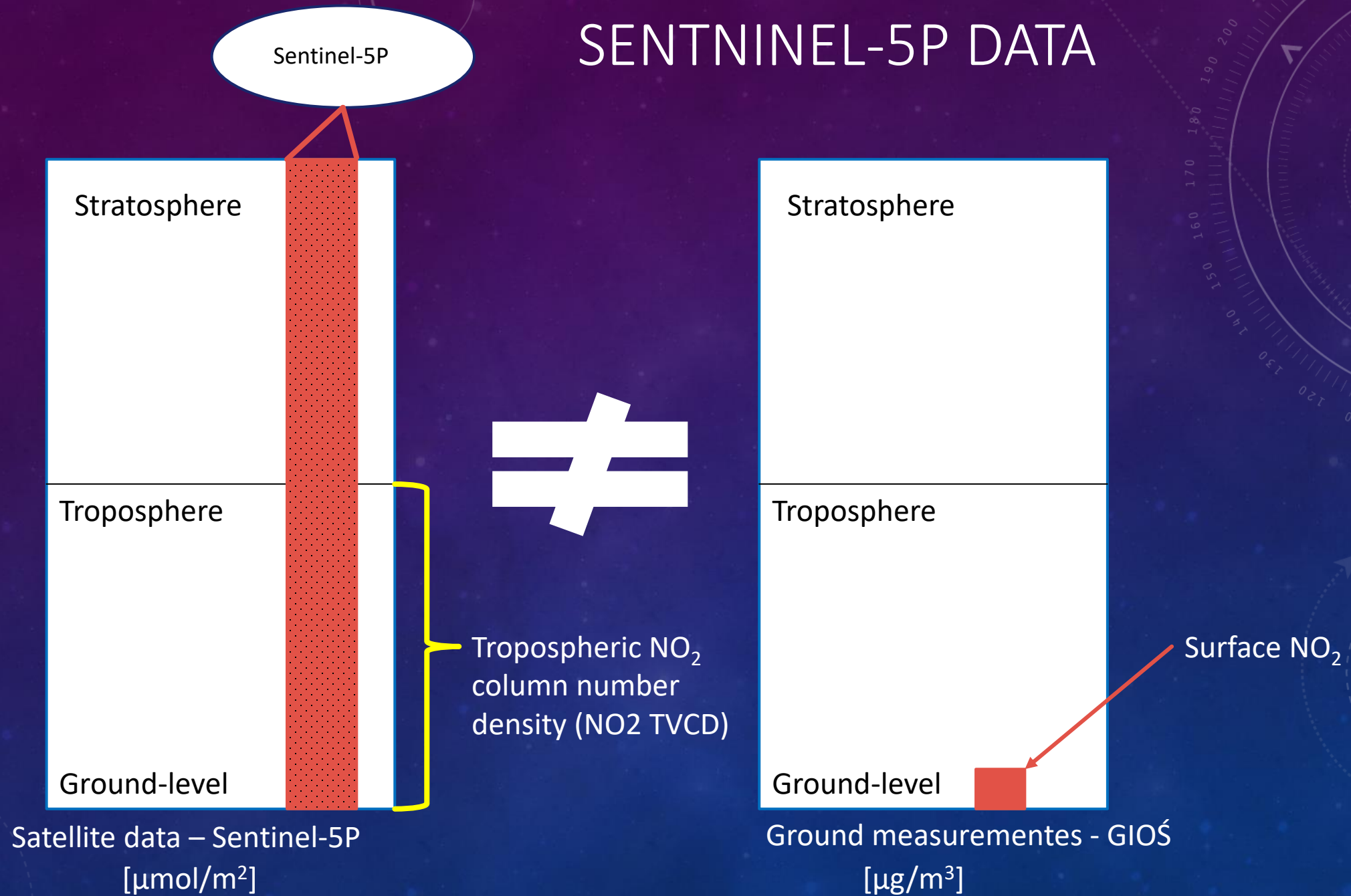
Ozone

Clouds

# RETRIEVAL AND GENERATION OF THE PRODUCT

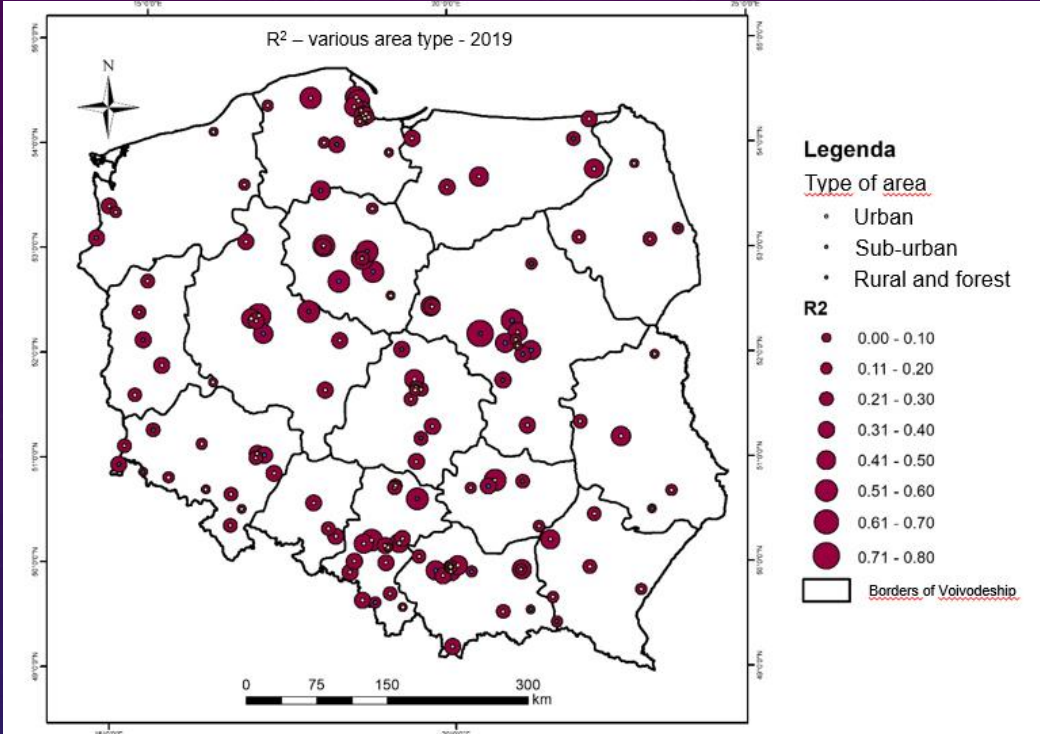
- 400-465 nm used for NO<sub>2</sub> retrieval;
- Generated by The Royal Netherlands Meteorological Institute (KNMI);
- Procedure:
  - Using Differential Optical Absorption Spectroscopy (DOAS) method NO<sub>2</sub> slant columns from the measured radiance and irradiance spectra is retrieved;
  - Separation of tropospheric and stratospheric columns. Conversion to tropospheric and stratospheric slant columns;
  - Conversion of tropospheric and stratospheric slant columns into tropospheric and stratospheric vertical column density (Boersma et al., 2011; van Geffen et al., 2015).
  - Vertical profiles of NO<sub>2</sub> are calculated for the center of a pixel featuring a spatial resolution of 1° × 1° and are based on the chemistry transport model (CTM)—TM5-MP (van Geffen et al., 2015; Williams et al., 2017).
  - Finally, filtering of cloud cover is performed by the Fast Retrieval Scheme for Clouds from the Oxygen A-band (FRESCO-S) algorithm (Loyola et al., 2020).
- Within this study, reprocessed Sentinel-5P TROPOMI NO<sub>2</sub> product (S5P-PAL) data was used (version 2.3.1)

# SENTNINEL-5P DATA



# Problems? Challenges?

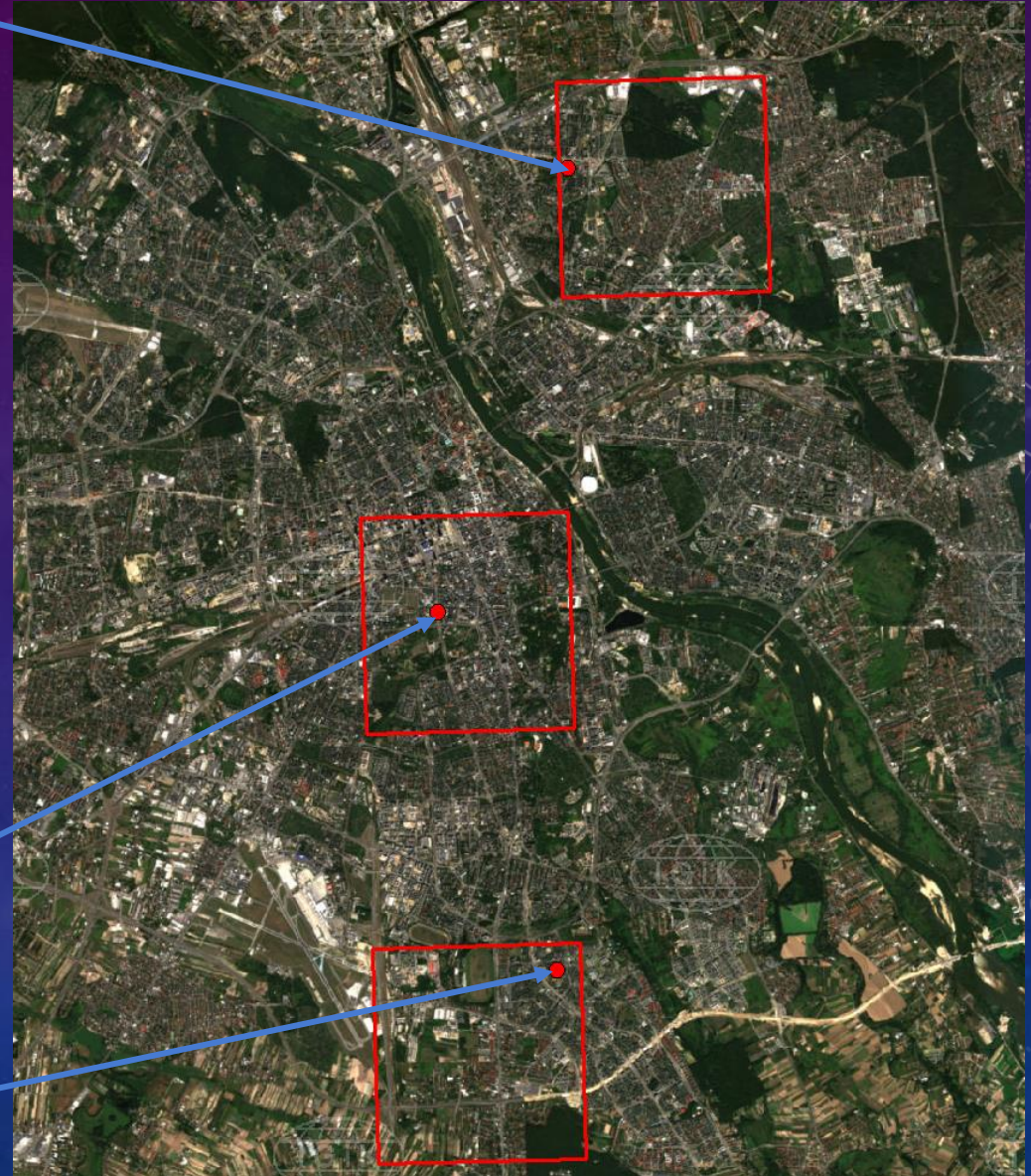
Kondratowicza



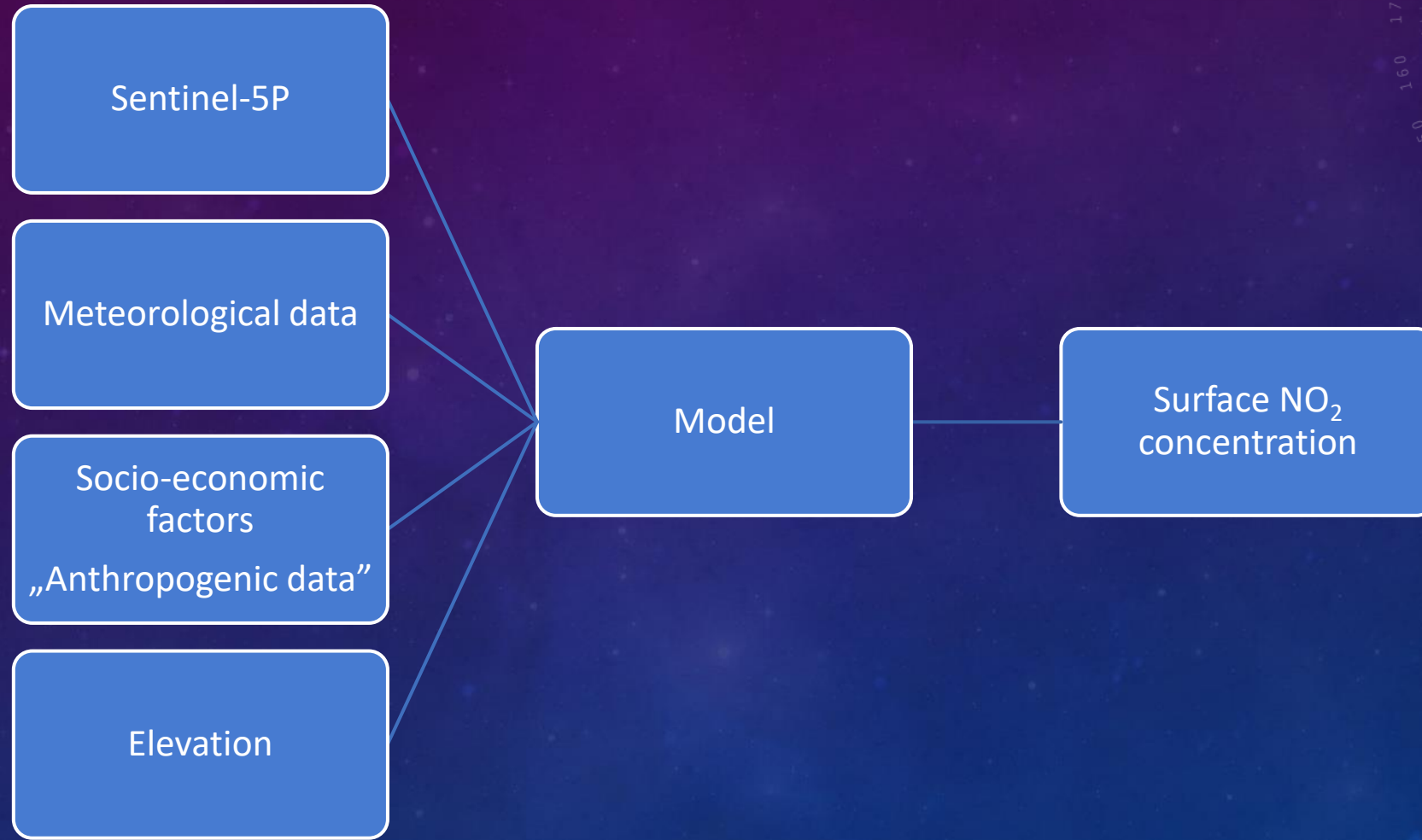
R<sup>2</sup> (Surface NO<sub>2</sub> vs. NO<sub>2</sub> TVCD) for each station in Poland

Al. Niepodległości

Wokalna



# WHAT IS GOING TO BE ACHIEVED?



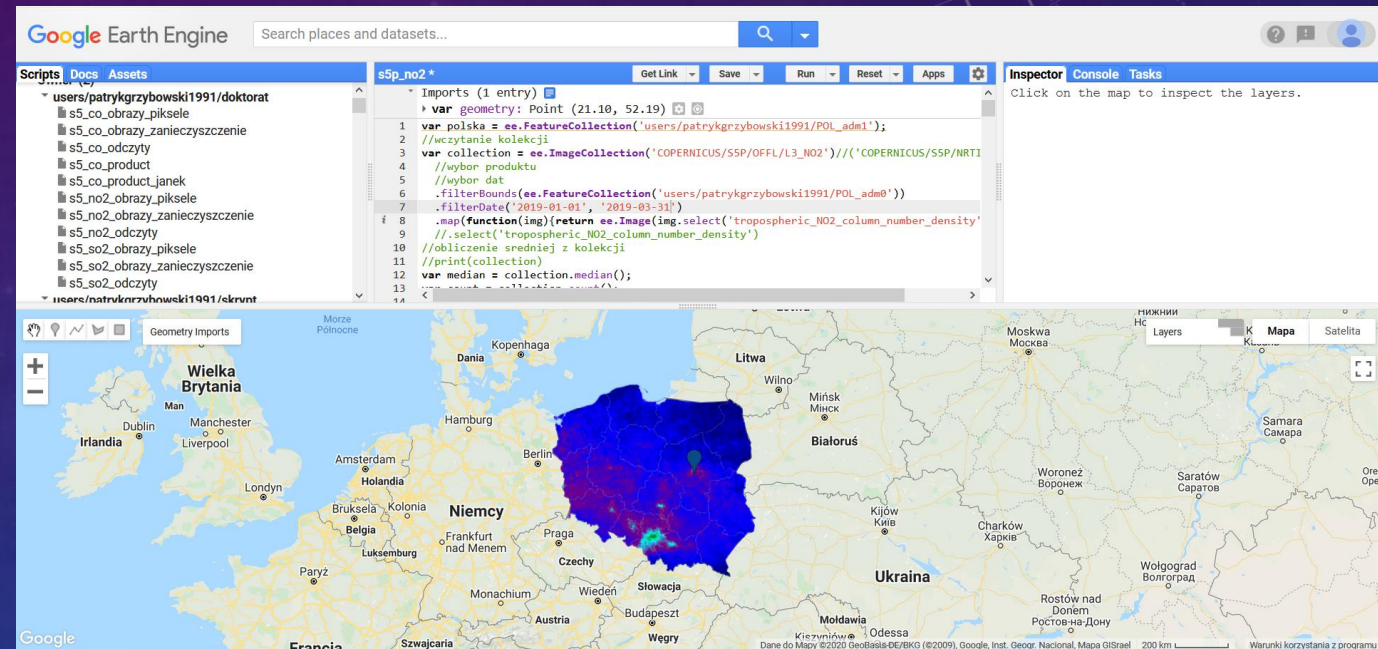


# DATA

Kind of data	Source	Data
Satellite data	Senitnel-5P – ESA, European Commission	NO2 TVCD
Ground-based concentration	GIOŚ	Surface NO2
Meteorolgical data	ECMWF	Temperature Dew point temperature Pressure Solar radiation accumulated by 1 hour U component of wind V component of wind Boundary layer height Relative humidity Wind speed Wind direction
	NCEP/NCAR	Sea level pressure
Socio-Economic data	NASA/EC JRC/NOAA	Population Nightlights
Geography	NASA	Elevation

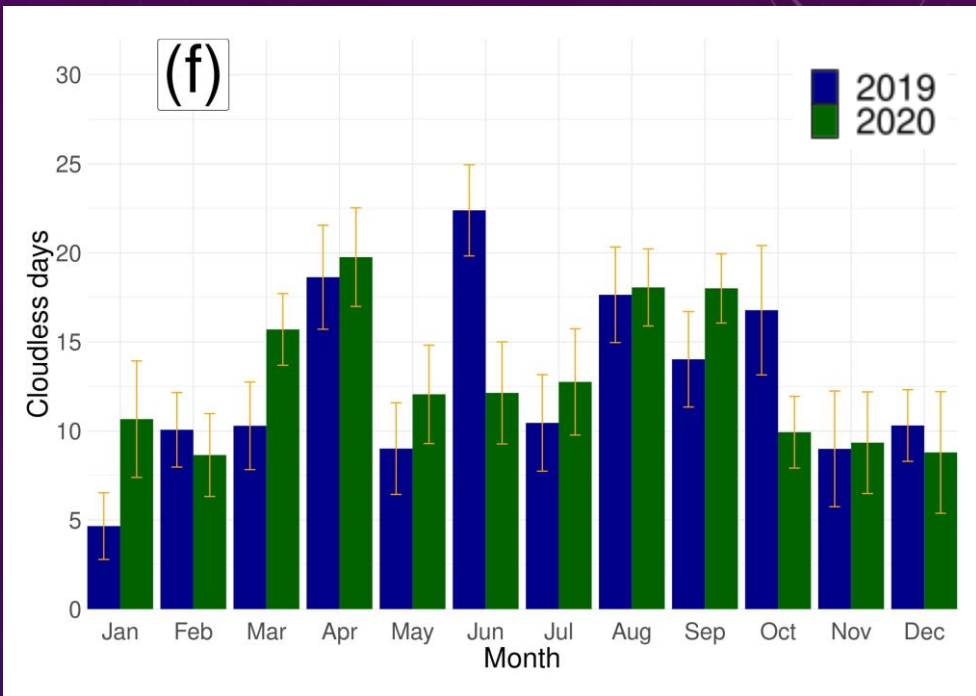
# DATA PROCESSING

- Platform based on the JavaScript programming language
- A platform for analyzing and visualizing geospatial datasets for academic, non-profit, business and government users
- It provides satellite data and stores it in a public data archive that includes historical images of the Earth from more than forty years ago. The images that are taken daily are then made available for data mining on a global scale.
- Earth Engine also provides APIs and other tools to analyze big data
- Provides easy access to a comprehensive catalog of satellite imagery and other geospatial data in an analysis-ready format. The data catalog is connected to the cloud computing supported by Google data centers and flexible APIs that allow you to seamlessly implement existing scripts and schemas. This enables state-of-the-art global analysis and visualization of geospatial data.



# DATA PRE-PROCESSING

- Time analysis: 07.2018-06.2021
  - 2019 and 2020 for availability of data
- Data was linearly interpolated to the time of S-5P acquisition
- Data has been resampled to spatial resolution 3.5 km x 5.5. km using bilinear interpolation
- Outliers:
  - Station measuring surface NO<sub>2</sub> was closer than 100 meters from the road (2 stations; 1 024 observations; 2% of all observations).
- Training dataset (22 678):
  - January, March, May, July, September, Novemeber
- Testing dataset (27 241):
  - February, April, June, August, October, December

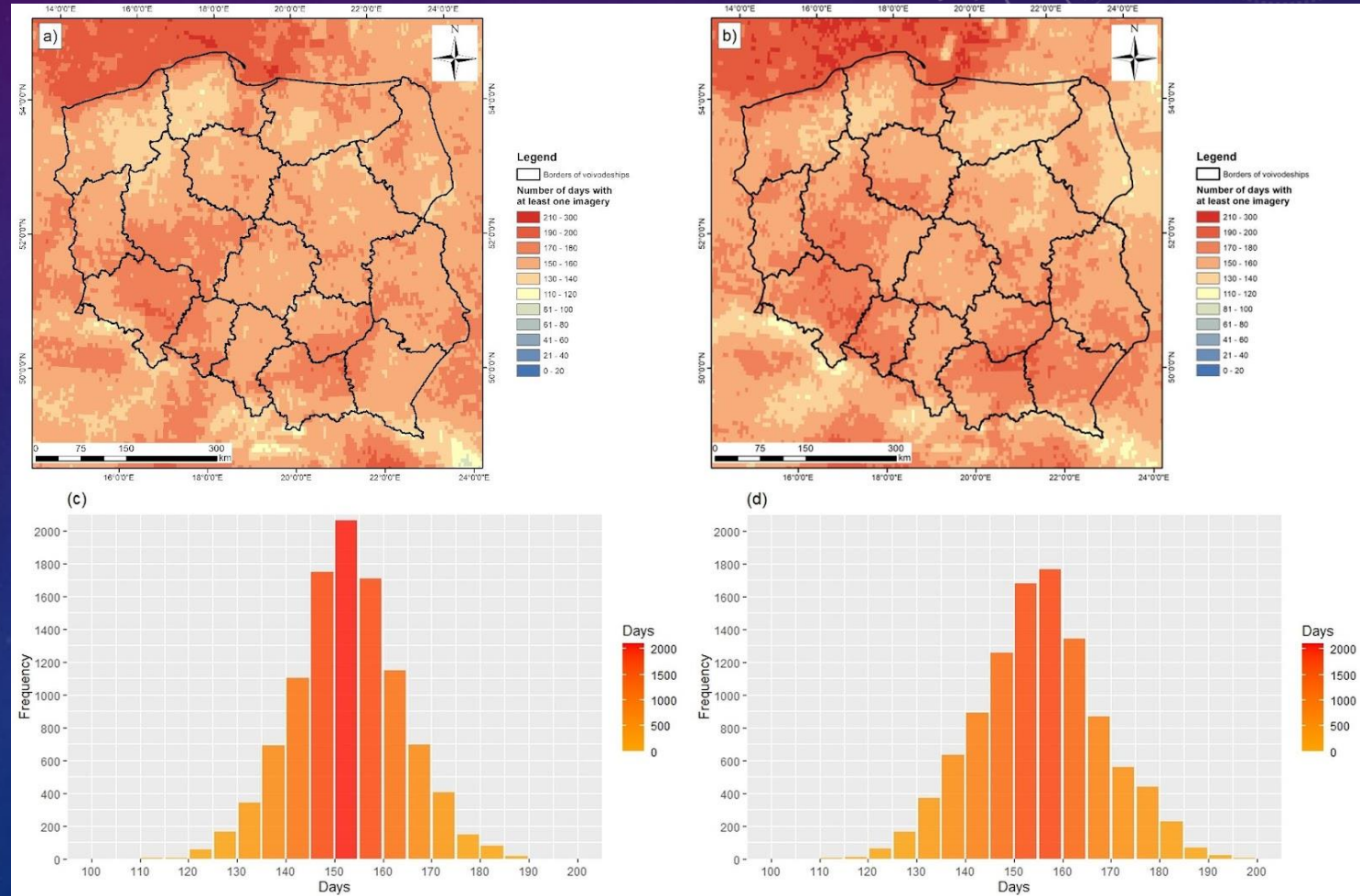


Average number of cloudless days over Poland in each month. Blue – 2019; green – 2020. Yellow bars are minimum and maximum cloudless days.

# KNOW THE LIMITATIONS

qa\_value  $\geq 0.75$   
 cloud fraction  $\leq 0.50$

Count of cloudless days in Poland in 2019 (a – map; c – histogram) and in 2020 (b – map; d – histogram)



# PREDICTION METHODS

Linear regression with one undependable variable (LM)

NO<sub>2</sub> TVCD

Multiple linear regression with several undependable variables (MLM)

NO<sub>2</sub> TVCD

Air temperature (T)

Pressure (P)

Solar radiation (RADNET)

Wind speed (WS)

Planetary boundary layer height (PBLH)

Nightlights (NIGHTLIGHT)

Population (POP)

Road density (ROADS)

Elevation (ELEVATION)

Random forest with several undependable variables (RF)

NO<sub>2</sub> TVCD

Air temperature (T)

Pressure (P)

Solar radiation (RADNET)

Wind speed (WS)

Planetary boundary layer height (PBLH)

Nightlights (NIGHTLIGHT)

Population (POP)

Road density (ROADS)

Elevation (ELEVATION)

Circulation type (CT)

Radial kernel support vector machine with several undependable variables (SVM)

NO<sub>2</sub> TVCD

Air temperature (T)

Pressure (P)

Solar radiation (RADNET)

Wind speed (WS)

Planetary boundary layer height (PBLH)

Nightlights (NIGHTLIGHT)

Population (POP)

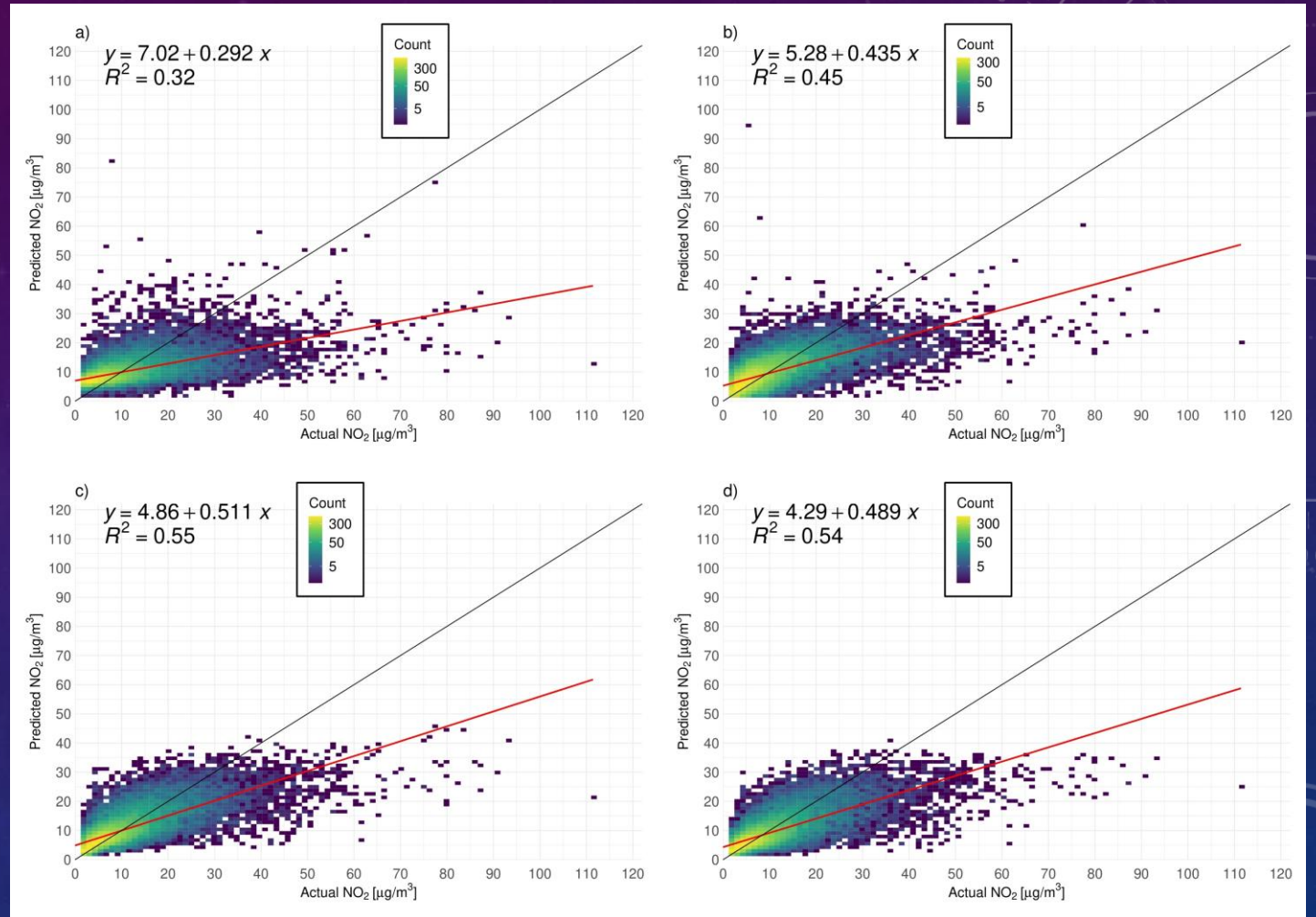
Road density (ROADS)

Elevation (ELEVATION)

Circulation type (CT)

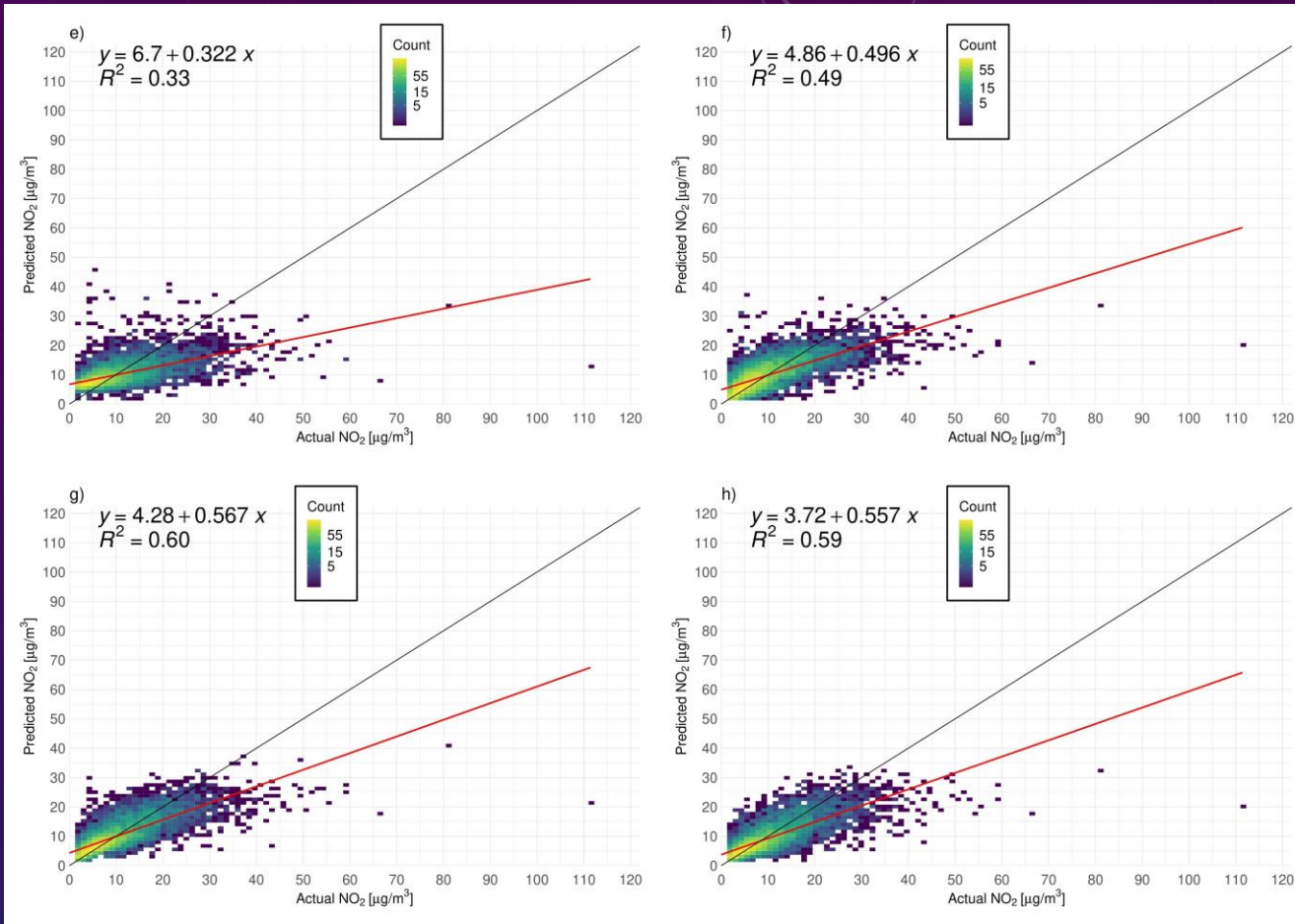
# PREDICTION OF SURFACE NO<sub>2</sub> - HOURLY

Surface NO <sub>2</sub> mass concentration estimations							
		MEAN	MIN	MAX	SD	1st Q	3rd Q
Testing dataset (n=27241)		10.07	0.01	111.41	8.89	4.40	13.12
Training dataset (n=22678)		10.44	0.01	100.59	8.61	4.44	12.93
Hourly measurements		R2	MSE	RMSE	Bias [ug/m3]	MAE [ug/m3]	MAPE [%]
	LM - S5P	0.32	53.22	7.30	0.11	4.87	48.38
	MLM	0.45	43.11	6.57	0.42	4.24	42.08
	RF	0.53	34.83	5.90	-0.04	3.74	37.15
	SVM	0.54	37.67	6.09	1.04	3.72	36.94



Results of prediction of surface NO<sub>2</sub> based on four methods: linear regression – LM-S5P (a); multilinear regression - MLM (b); random forest - RF (c) and support vector machine - SVM (d)

# PREDICTION OF SURFACE NO<sub>2</sub> – WEEKLY AVERAGES

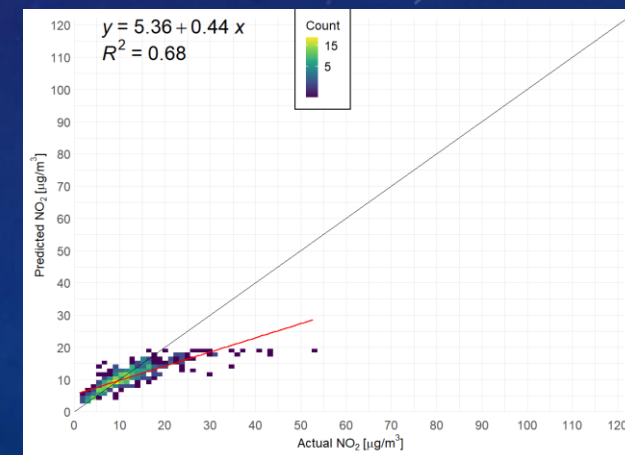
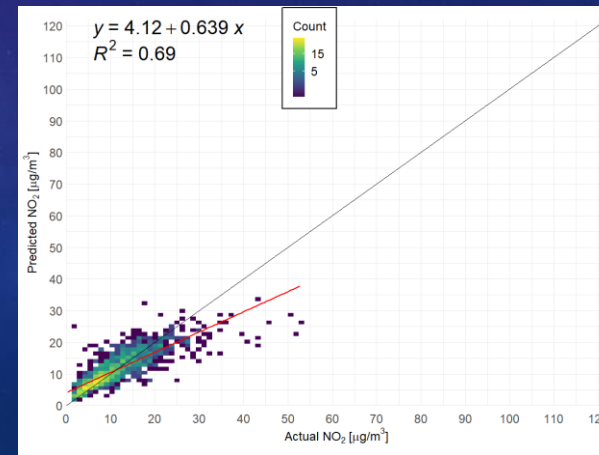
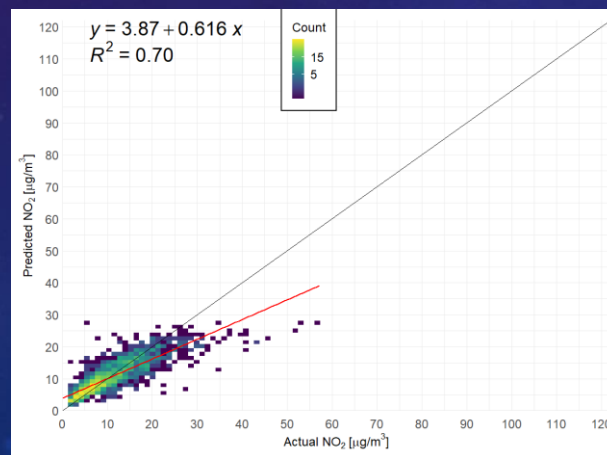
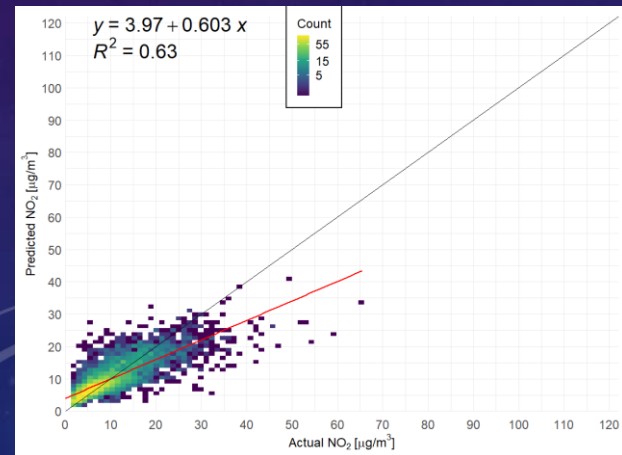


Results of prediction of surface NO<sub>2</sub> based on four methods: linear regression – LM-S5P (a); multilinear regression - MLM (b); random forest - RF (c) and support vector machine - SVM (d)

Surface NO <sub>2</sub> mass concentration estimations							
		MEAN	MIN	MAX	SD	1st Q	3rd Q
	<b>Testing dataset (n=6639)</b>	10.07	0.01	111.41	8.89	4.40	13.12
	<b>Training dataset (n=7126)</b>	10.44	0.01	100.59	8.61	4.44	12.93
<b>Weekly averages</b>		<b>R2</b>	<b>MSE</b>	<b>RMSE [ug/m3]</b>	<b>Bias [ug/m3]</b>	<b>MAE [ug/m3]</b>	<b>MAPE [%]</b>
	<b>LM - S5P</b>	0.33	38.09	6.17	0.14	4.27	42.37
	<b>MLM</b>	0.49	28.96	5.38	0.23	3.59	35.53
	<b>RF</b>	0.60	23.08	4.81	-0.09	3.10	30.75
	<b>SVM</b>	0.59	24.34	4.93	0.76	3.15	31.21

# MONTHLY, SEASONLY, YEARLY AVERAGES

	R <sup>2</sup>	MSE	RMSE [ug/m3]	BIAS [ug/m <sup>3</sup> ]	MAE [ug/m <sup>3</sup> ]	MAPE [%]
<b>HOURLY</b>	0.53	34.83	5.90	-0.04	3.74	37.15
<b>WEEKLY</b>	0.60	23.08	4.81	-0.09	3.10	30.75
<b>TWO WEEKLY</b>	0.63	19.14	4.38	-0.07	2.96	29.00
<b>MONTHLY</b>	0.71	15.51	3.94	-0.31	2.58	23.49
<b>SEASONLY</b>	0.69	15.72	3.97	-0.08	2.63	23.57
<b>YEARLY</b>	0.68	20.42	4.52	-1.24	2.50	21.22





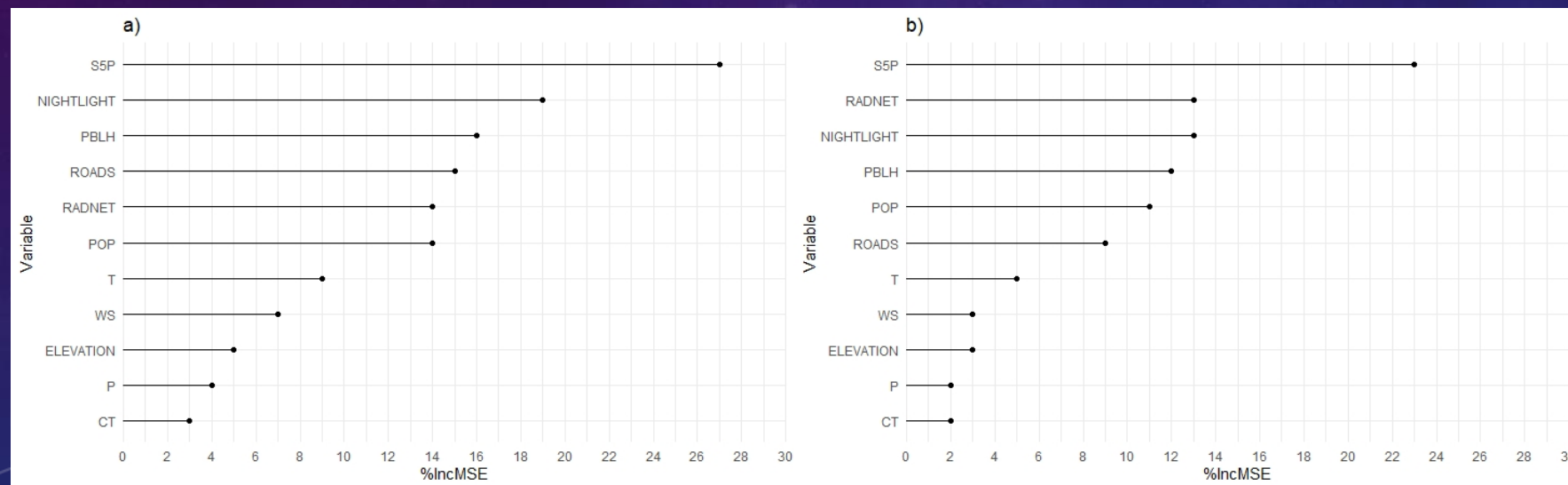
# VARIABLES' IMPORTANCE

## Multilinear regression

Variable	S5P	T	P	RAD	WS	PBLH	NIGHTLIGHT	POP	ROADS	ELEVATION	INTERCEPT
<b>Coefficient hourly</b>	0.62 (57%)	-0.01 (1%)	-0.03 (3%)	-0.06 (6%)	-0.07 (6%)	-0.08 (7%)	0.05 (5%)	0.03 (3%)	0.06 (6%)	0.01 (1%)	0.07 (6%)
<b>Coefficient weekly</b>	0.69 (53%)	-0.04 (3%)	-0.04 (3%)	-0.06 (5%)	-0.07 (5%)	-0.10 (8%)	0.06 (5%)	0.04 (3%)	0.08 (6%)	0.01 (1%)	0.10 (8%)

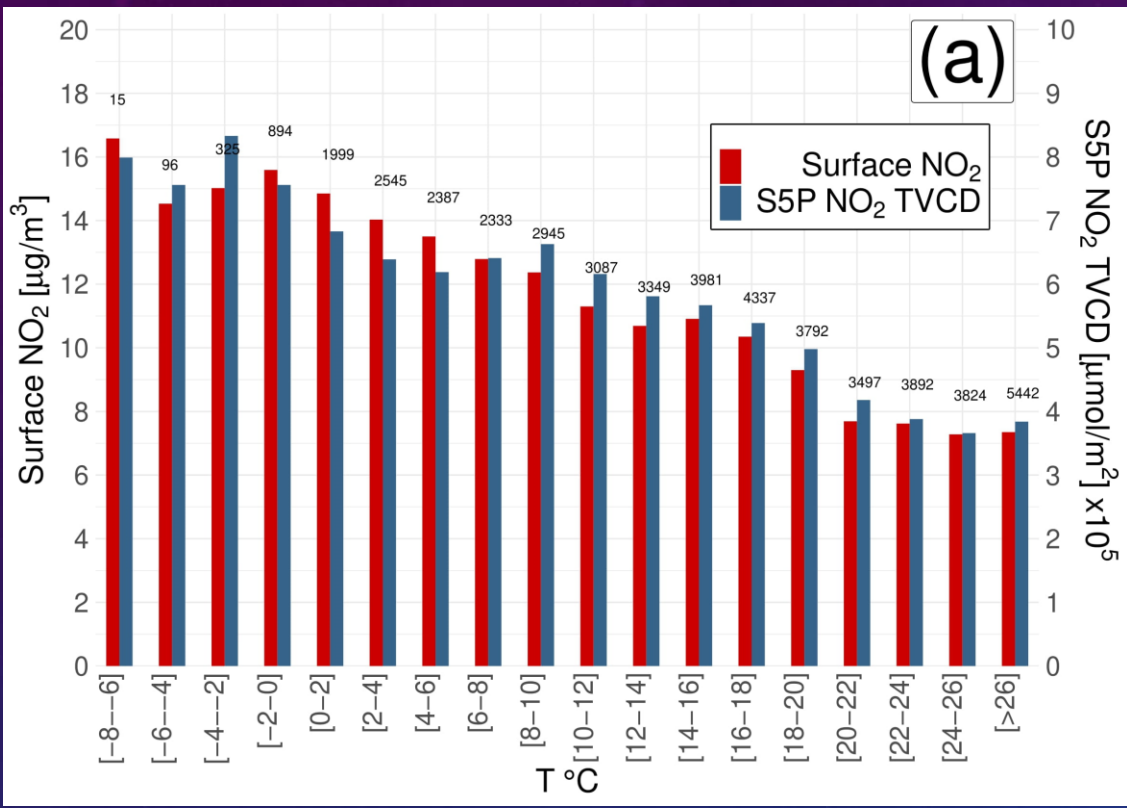
1. Standardization of variables
2. Sum of coefficients (absolute values)
3. Percentage of each coefficient within the sum

## Random Forest

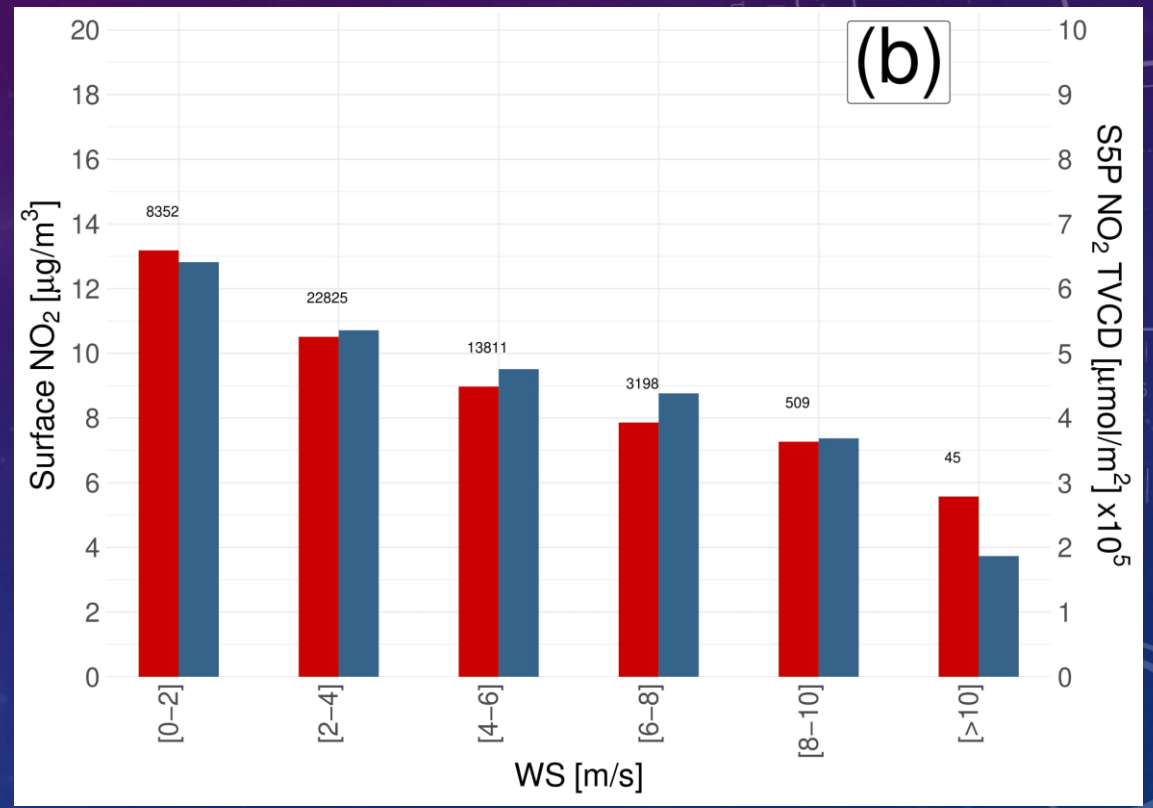


1. Compute model MSE;
2. For each variable in the model:
  - 1) Permute variable
  - 2) Calculate new model MSE according to variable permutation
  - 3) Take the difference between model MSE and new model MSE

# CHANGES IN NO2 TVCD AND SURFACE NO2 MASS CONCENTRATION IN RESPECT TO METEOROLOGICAL CONDITIONS



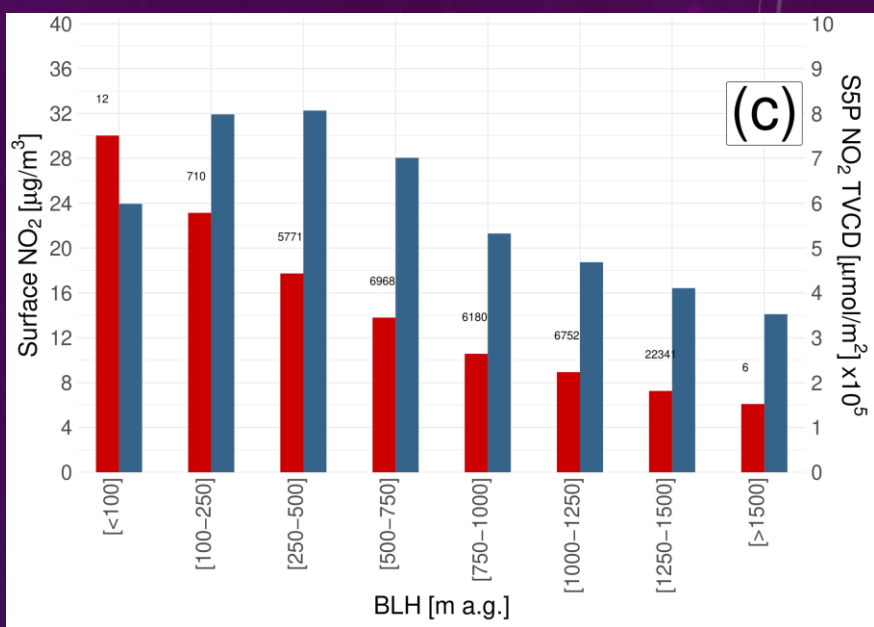
Change of air pollution in respect to air temperature



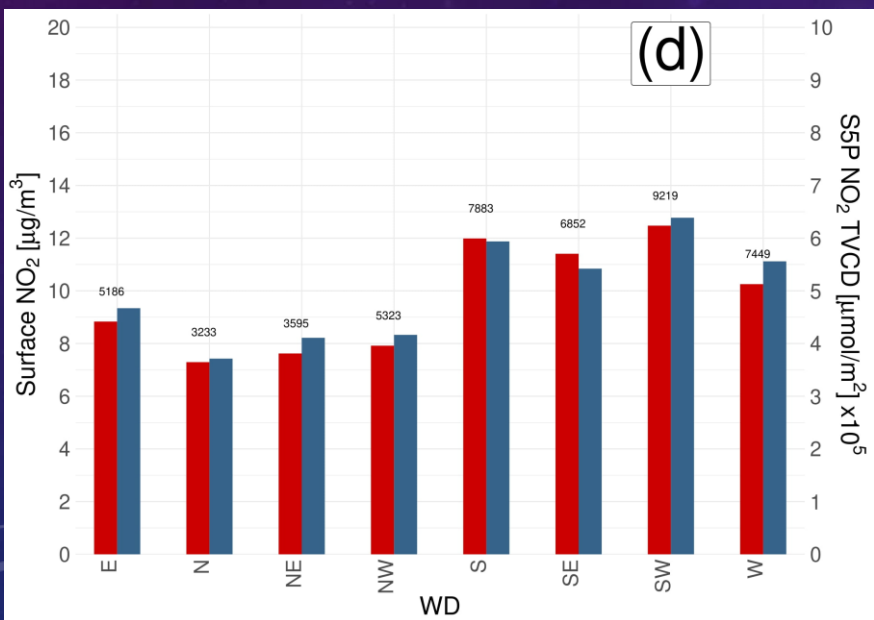
Change of air pollution in respect to wind speed

Left y axis, red font and red bars correspond to surface NO<sub>2</sub> mass concentration while the right y axis, blue font and blue bars correspond to TVCD of NO<sub>2</sub>.

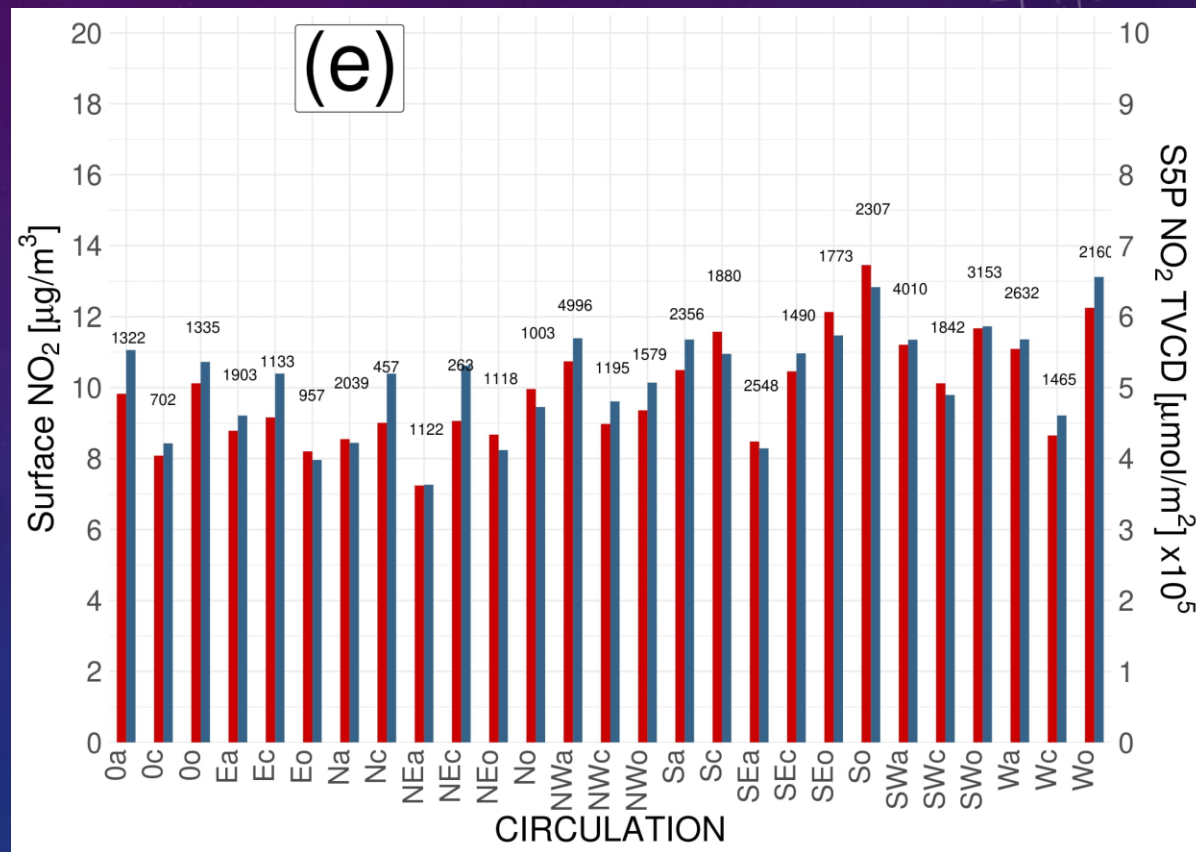
# CHANGES IN NO<sub>2</sub> TVCD AND SURFACE NO<sub>2</sub> MASS CONCENTRATION IN RESPECT TO METEOROLOGICAL CONDITIONS AND OTHER FACTORS



Change of air pollution in respect to PBLH



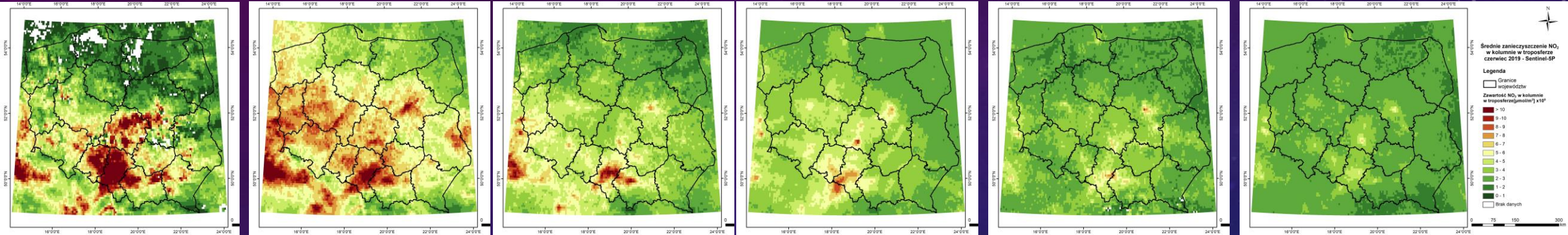
Change of air pollution in respect to wind direction



Change of air pollution in respect to type of atmospheric circulation

Left y axis, red font and red bars correspond to surface NO<sub>2</sub> mass concentration while the right y axis, blue font and blue bars correspond to TVCD of NO<sub>2</sub>.

# SPATIO-TEMPORAL CHANGES



January

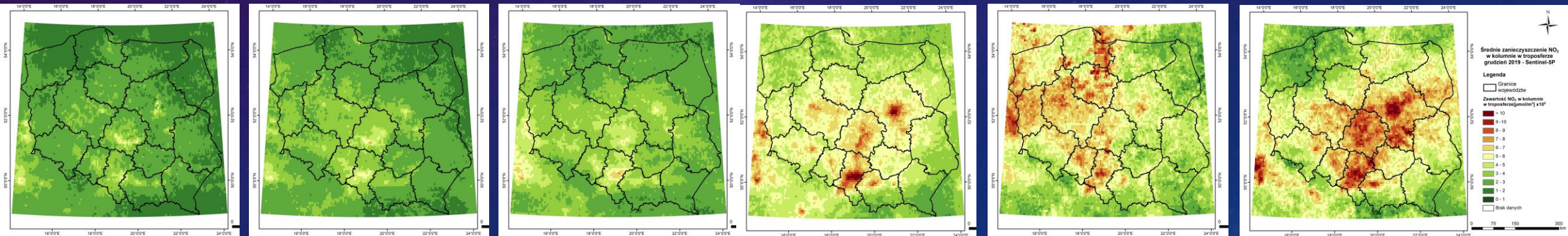
February

March

April

May

June



July

August

September

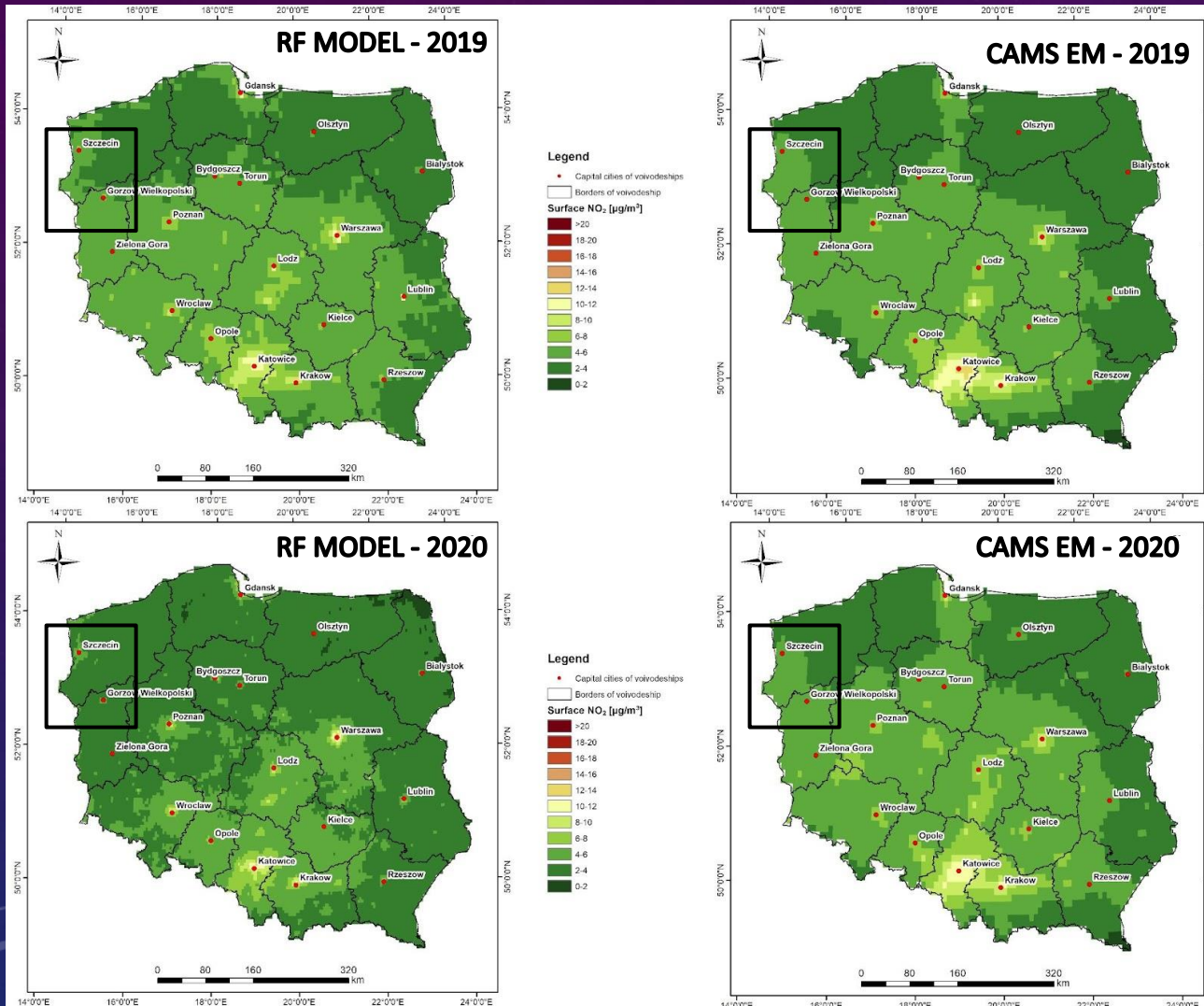
October

November

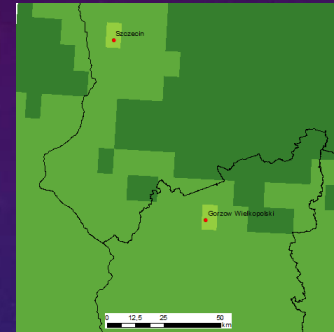
December

Spatio-temporal variabilities of NO<sub>2</sub> TVCD over Poland in 2019.

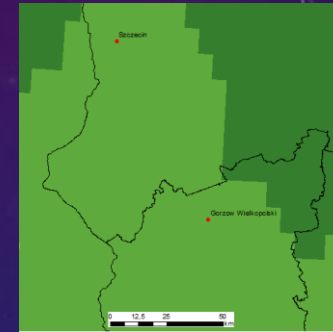
# COMPARISON WITH CAMS ENSEMBLE MEDIAN (CAMS EM)



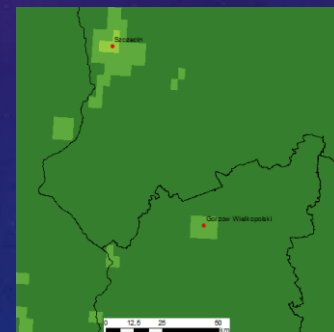
RF MODEL - 2019



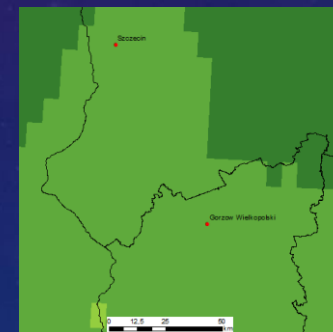
CAMS EM - 2019



RF MODEL - 2020



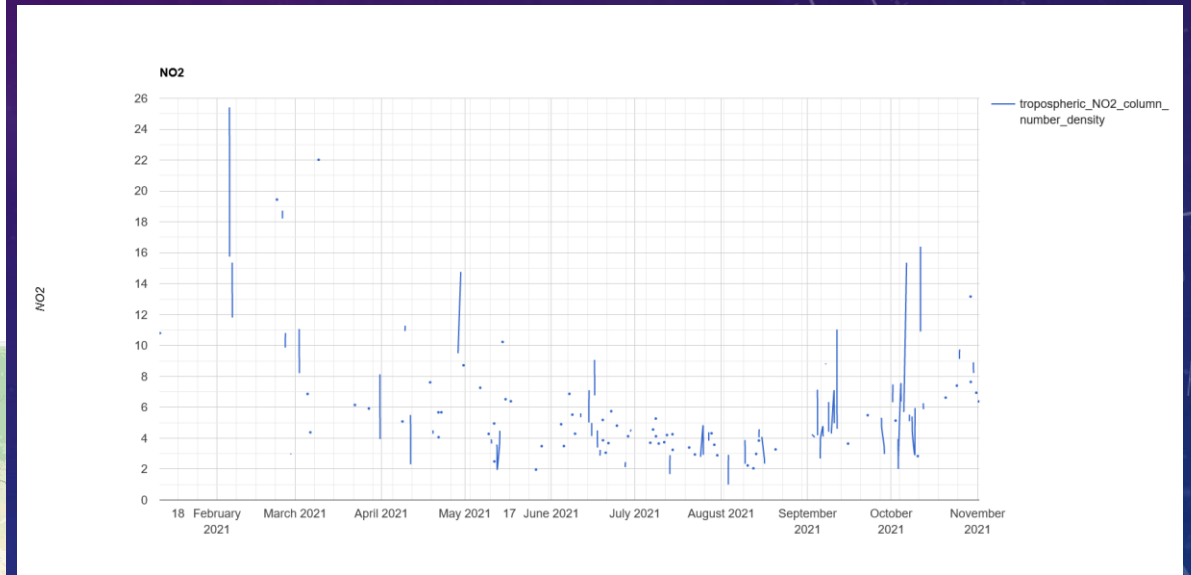
CAMS EM - 2020



	MAE [ug/m3]	MAPE [%]	R2
RF	3,87	37,96	0,54
CAMS	5,37	52,74	0,46

# APP

```
Scripts Docs Assets wykres_widget Inspector Console Tasks
#s5_no2_dekady_zanieczyszczenie 1 //granice Polski
#s5_no2_nowa_dekada 2 var polska = ee.FeatureCollection('users/patrykgrzybowski1991/POL_adm1');
#s5_no2_nowy_ydzien 3 //wczytanie kolekcji
#s5_no2_obrazy_piksele 4 var collection_no2 = ee.ImageCollection('COPERNICUS/SSP/NRTI/L3_NO2')/('COPERNICUS/SSP/NRTI/L3_NO2')
#s5_no2_obrazy_piksele_2018 5 //wybor produktu
#s5_no2_obrazy_piksele_2018_months 6 //wybor dat
#s5_no2_obrazy_piksele_2019_months 7 .filterBounds(ee.FeatureCollection('users/patrykgrzybowski1991/POL_adm0'))
#s5_no2_obrazy_piksele_2020 8 .filterDate('2021-01-01', ee.Date(new Date().getTime()))
#s5_no2_obrazy_zanieczyszczenie 9 .map(function(img){return ee.Image(img.select('tropical_NO2_column_number_density')
#s5_no2_obrazy_zanieczyszczenie 10 .multiply(1000000))
#s5_no2_obrazy_zanieczyszczenie 11 .updateMask(img.select('cloud_fraction').lt(0.4))
#s5_no2_obczy_katy 12 .set('system:time_start', img.get('system:time_start'));
#s5_no2_obczy_katy 13 }) //select('tropical_NO2_column_number_density')
#s5_no2_obczy_katy 14
#s5_no2_obczy_katy 15 var panel = ui.Panel();
#s5_no2_obczy_katy 16 panel.style().set('width', '300px');
#s5_no2_obczy_katy 17
#s5_no2_obczy_katy 18 // Create an intro panel with labels.
#s5_no2_obczy_katy 19 var intro = ui.Panel({
#s5_no2_obczy_katy 20 ui.Label({
#s5_no2_obczy_katy 21 value: 'Time Series Chart Inspector',
#s5_no2_obczy_katy 22 style: {fontSize: '28px', fontWeight: 'bold'}
#s5_no2_obczy_katy 23 });
#s5_no2_obczy_katy 24 ui.Label('Click a point on the map to inspect.')}
#s5_no2_obczy_katy 25 );
#s5_no2_obczy_katy 26 panel.add(intro);
#s5_no2_obczy_katy 27
#s5_no2_obczy_katy 28 var lon = ui.Label();
#s5_no2_obczy_katy 29 var lat = ui.Label();
#s5_no2_obczy_katy 30 panel.add(ui.Panel([lon, lat], ui.Panel.Layout.Flow('horizontal')));
#s5_no2_obczy_katy 31
#s5_no2_obczy_katy 32 Map.onClick(function(coords) {
#s5_no2_obczy_katy 33 // Update the lon/lat panel with values from the click event.
#s5_no2_obczy_katy 34 lon.setValue('lon: ' + coords.lon.toFixed(2));
#s5_no2_obczy_katy 35 lat.setValue('lat: ' + coords.lat.toFixed(2));
#s5_no2_obczy_katy 36 var point = ee.Geometry.Point(coords.lon, coords.lat);
```



# CONCLUSIONS

- There were at least 120 days per year when it was possible to perform model for Poland using TROPOMI observations
- Results revealed machine learning methods (RF and SVM) gave accuracy 63% for hourly estimation and 69% for weekly averages
- Implementation of meteorological and anthropogenic variables extremely improved the quantity of models. MLM approach gives 6% (hourly) and 7% (weekly) lower MAPE than LM-S5P approach while RF and SVM approaches gives 11% (hourly) and 12% (weekly) lower MAPE than LM-S5P
- NO<sub>2</sub>, TVCD, Planetary boundary layer height, solar radiation, nightlights, roads density and population influenced on estimations the most
- Air temperature, wind speed, surface pressure, elevation and type of atmospheric circulation influenced on estimation the least
- Trends for surface NO<sub>2</sub> and TVCD of NO<sub>2</sub> were negative for raising air temperature, PBLH and wind speed while they were positive for rising of population and nightlights
- The RF model created within the study was better fitted to actual values than CAMS ensemble median

## FURTHER ACTIVITIES

- Station's representativeness in respect to area of TROPOMI pixel

Thank you for your attention!

