

Adaptive Time-Stepping within the Super-Droplet Method Monte-Carlo Coagulation

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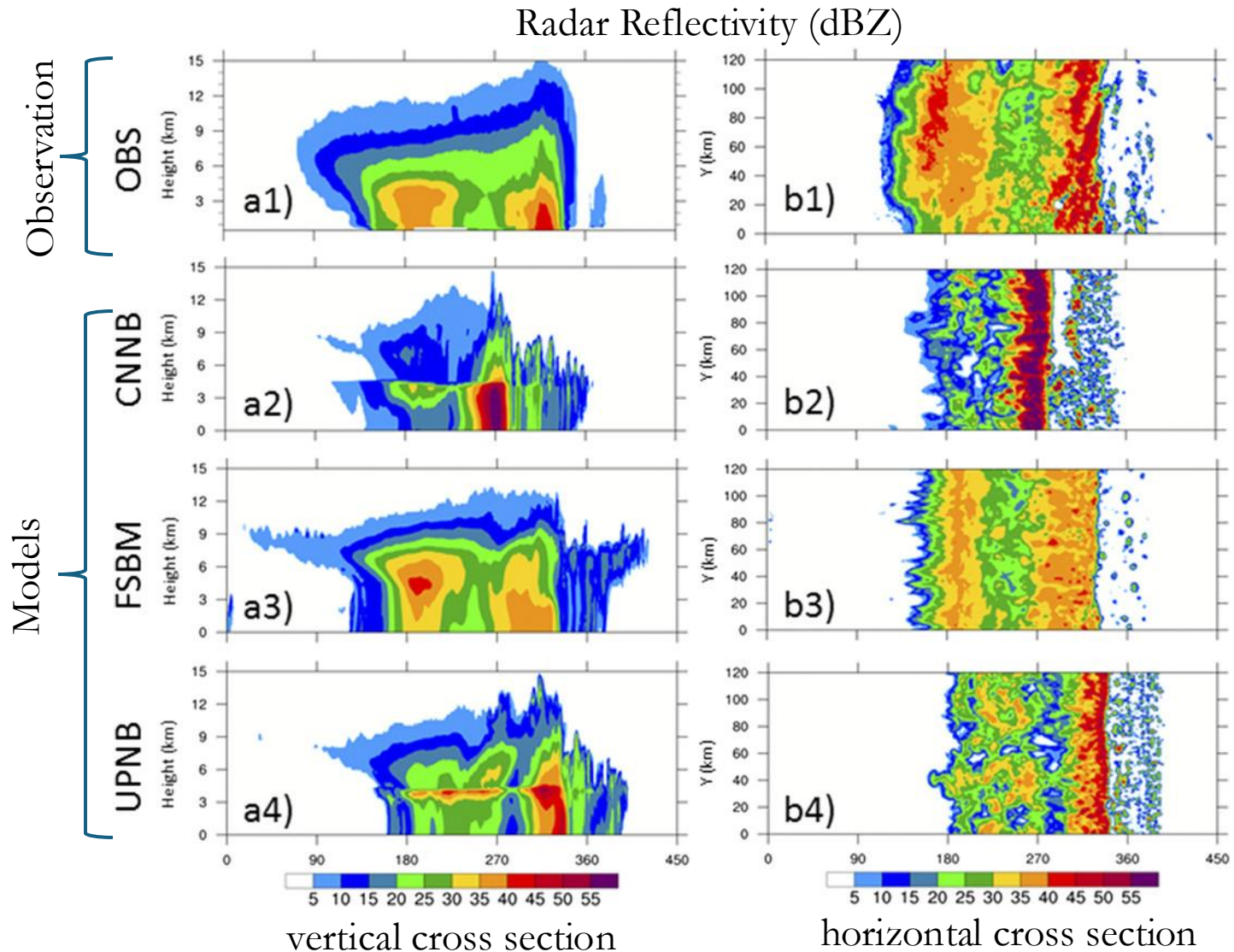
- **Background on Cloud Processes**
- Superdroplet Method for collision coalescence
- Defining the Deficit Problem/Adaptive Timestepping
- Adaptivity in a Box model
- Adaptivity in 2d prescribed flow

Clouds are important and hard to model accurately!

- Weather Forecasting
- Radiation Budget and Climate

We need accurate and efficient representation of cloud microphysical properties and dynamics

Understanding small scale processes leads to accurate parameterizations of larger ones!!!!

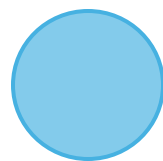




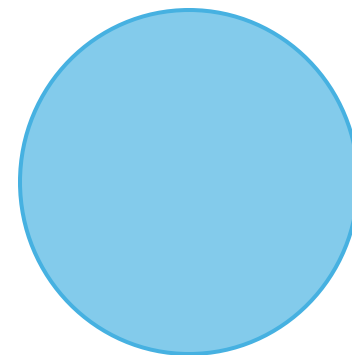
Aerosol particle
 $\approx \leq 2 \mu m$



cloud droplet
 $\approx > 2 \mu m$



drizzle droplet
 $> 50 \mu m$

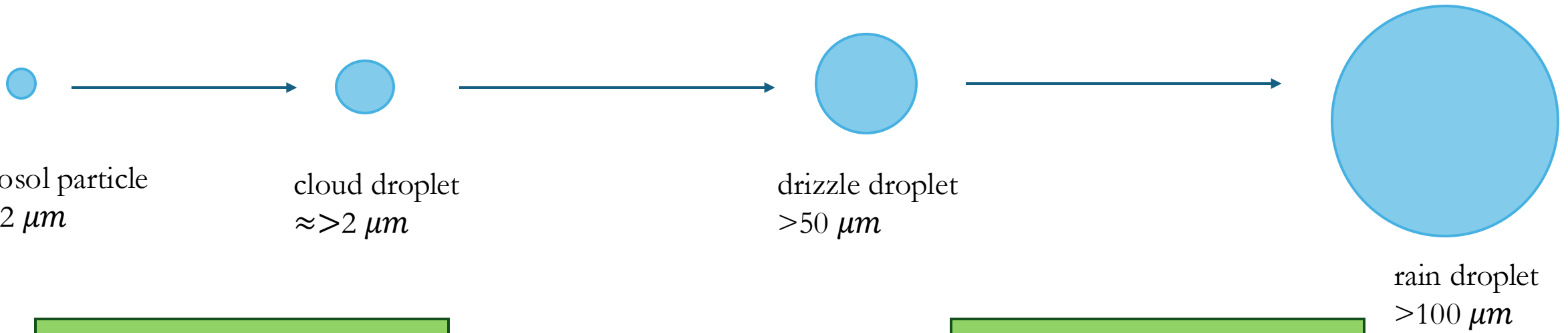


rain droplet
 $> 100 \mu m$



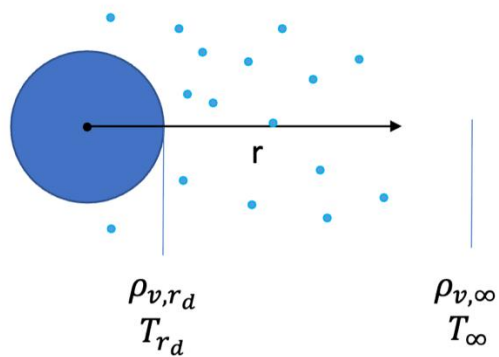
Condensation

Collision-Coalescence



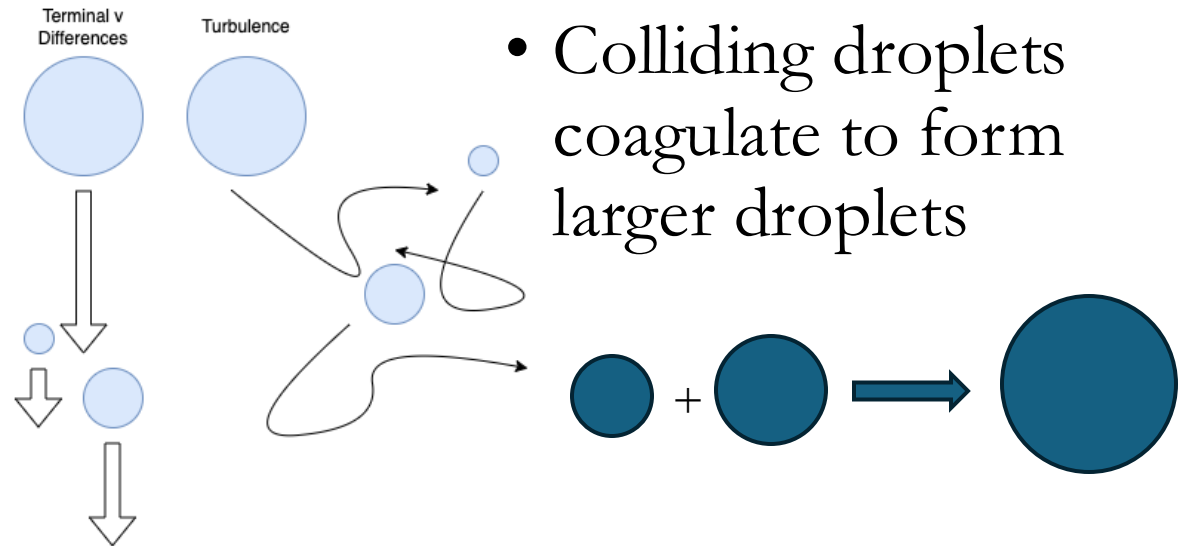
Condensation

- Diffusional Growth
- Fick's Law



Collision-Coalescence

- Colliding droplets coagulate to form larger droplets

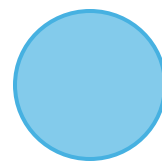




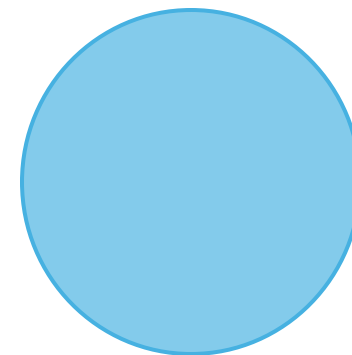
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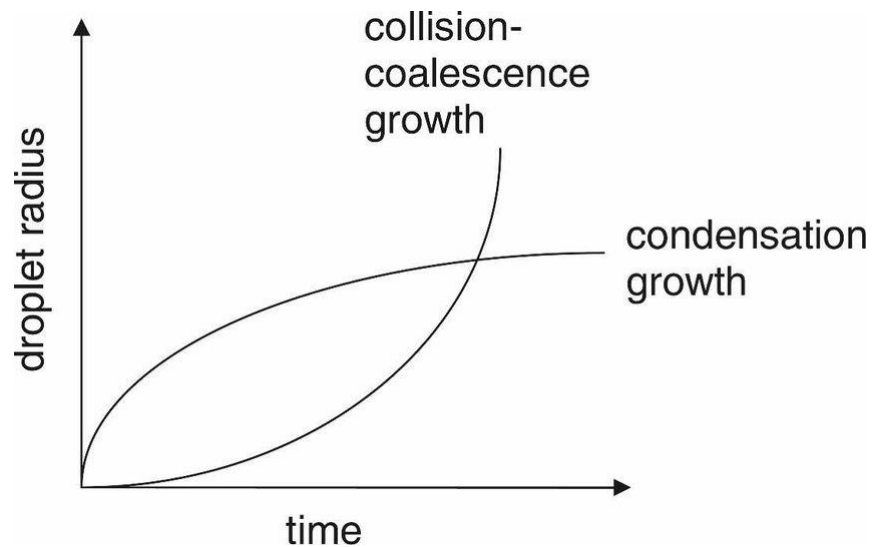
drizzle droplet
 $> 50 \mu m$



rain droplet
 $> 100 \mu m$

Condensation

Collision-Coalescence



It would take a $2 \mu m$ activated cloud droplet **24 hours** to grow into $100 \mu m$ raindrop in average conditions through condensation alone

Smoluchowski Coagulation Equation

$$\frac{\partial n(x, t)}{\partial t} = \frac{1}{2} \int_0^x K(x - y, y) n(x - y, t) n(y, t) dy - \int_0^\infty K(x, y) n(x, t) n(y, t) dy.$$

GAIN

LOSS

Change in # particles of
size X

=

Smaller particles colliding
to become size X

-

Particles leaving size X due
to collisions with other
particles

$K(R_i, R_j)$: *Kernel*(j, k), describes the likelihood of these interactions happening

Smoluchowski Coagulation Equation

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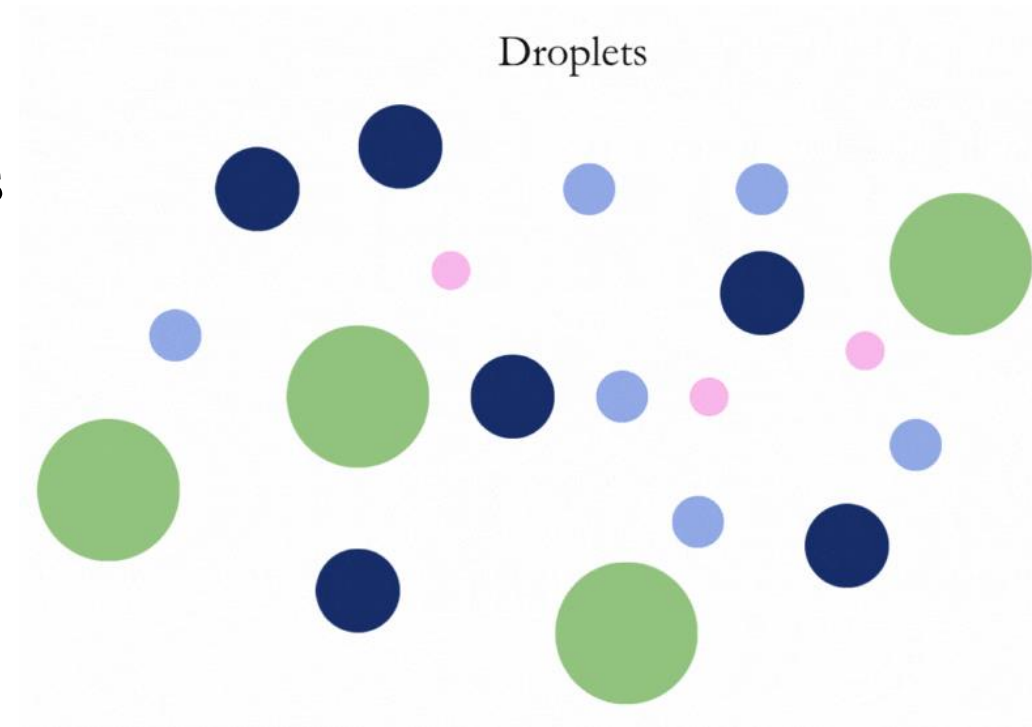
Particles leaving size X due
to collisions with other
particles

- Clouds
- Aerosol
- Shrimp Populations
- Fuel in pistons

- Bubbles
- Oil Spills
- Planetary Formation from dust

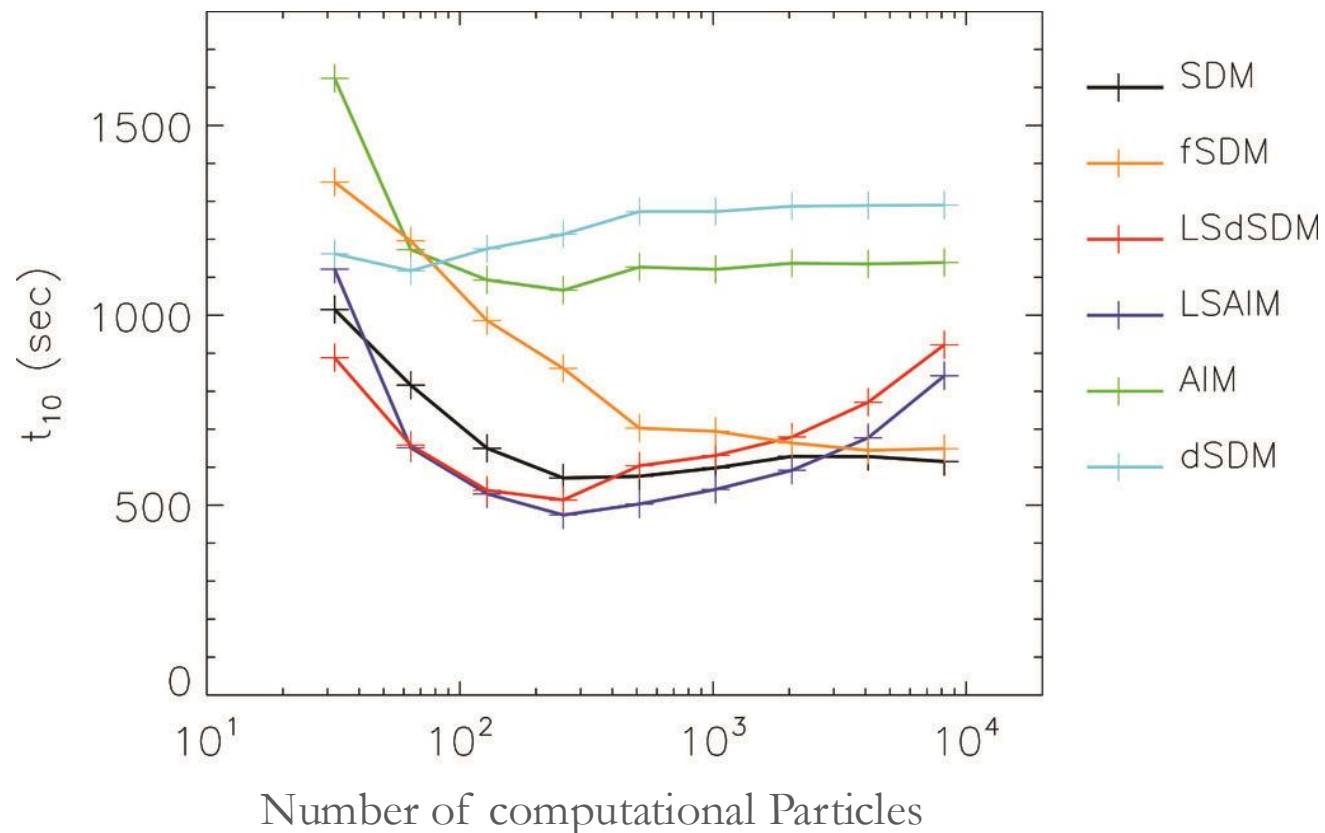
Particle-Based Methods (Superdroplets)

- Lagrangian tracers
- One computational superdroplet represents many computational droplets
- These particles can have attributes such as radius, isotopic composition, chemical composition, hygroscopicity, position
- Retain histories
- Well suited for Monte-Carlo coagulation algorithms



Still huge variability *just* in coagulation algorithms!!

t_{10} = time for 10% of system cloud water mass to reach “raindrop” size ($>40\mu\text{m}$)

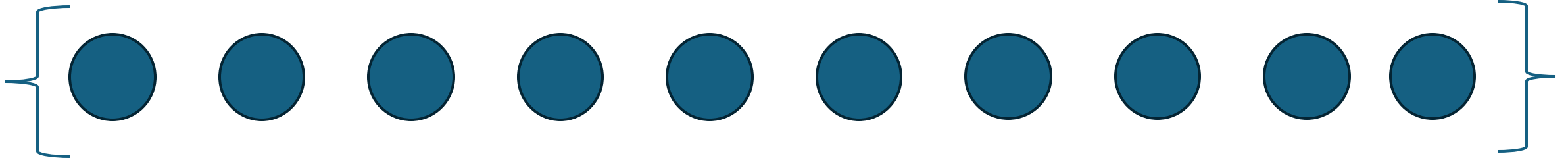


- 3D LES Cumulus Congestus Cloud
- Using piggybacking technique to separate microphysical behavior
- This shows variations on the Super Droplet Method (SDM, Shima et al., 2009) and Average Impact Method (AIM, Riechermann et al. 2012)
- Everything here is a particle-based representation

- Background on Cloud Processes
- **Superdroplet Method for collision coalescence**
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Super Droplet Method (Shima et al. 2009)

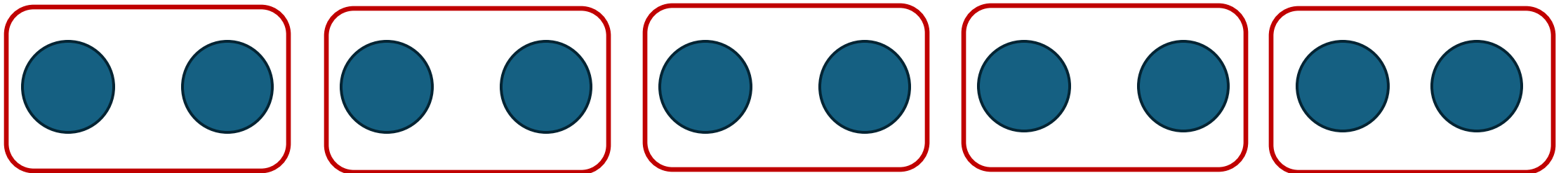
- When initialized efficiently, it is shown to outperform other algorithms in terms of convergence to analytic solutions (Unterstrasser et al, 2017)
- Monte-Carlo algorithm
- Tests pairs of superdroplets for collision events
- SDM Stochasticity resolves lucky rain formation (Morrison et al., 2024)

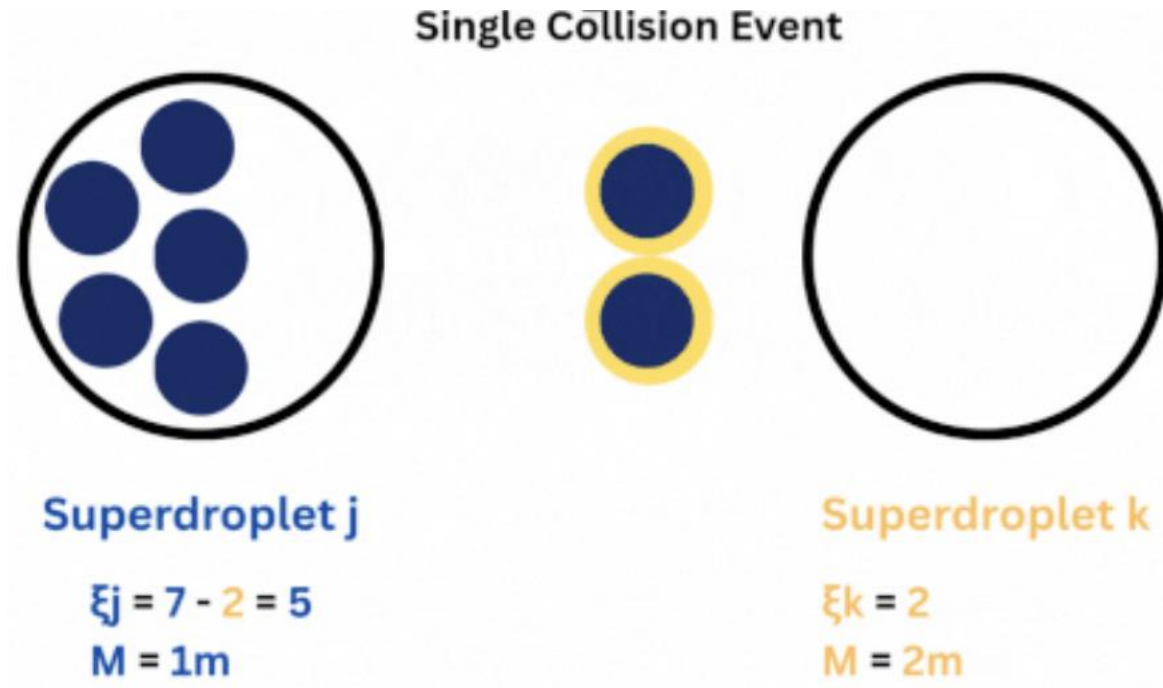


Super Droplet Method (Shima et al. 2009)

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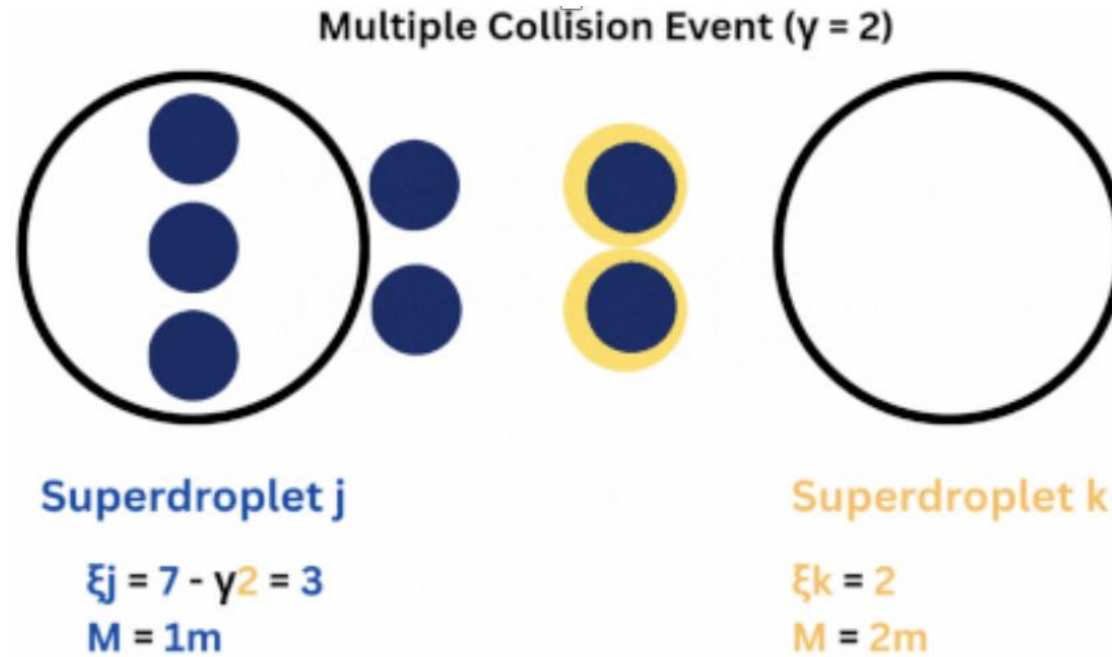
$$p_{pairj,k} = \frac{timestep}{collision\ volume} \cdot \xi_j \cdot \frac{total\ pairs}{pairs\ tested} \cdot Kernel(j,k), \quad \text{choosing } \xi_j > \xi_k$$





- Choosing j and k so that $\xi_j > \xi_k$
- Superdroplet k collects ξ_k droplet from donator superdroplet j
- Superdroplet k grows in mass, superdroplet j decreases multiplicity

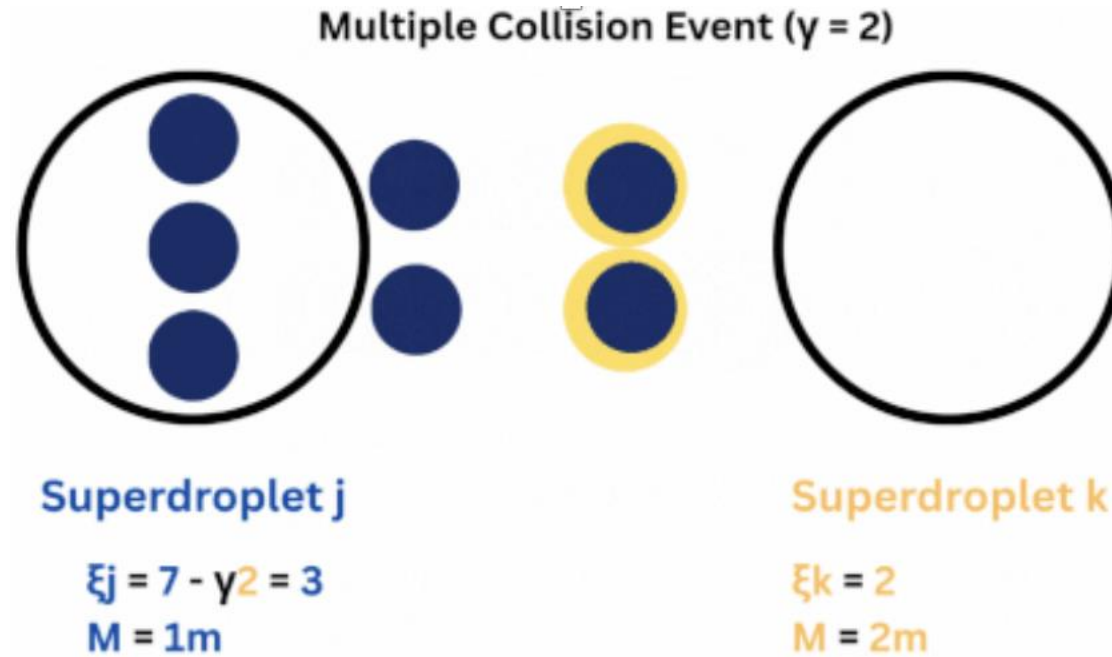
Mass and number of superdroplets are conserved



γ = integer number of events
predicted by probability
and Monte-Carlo success

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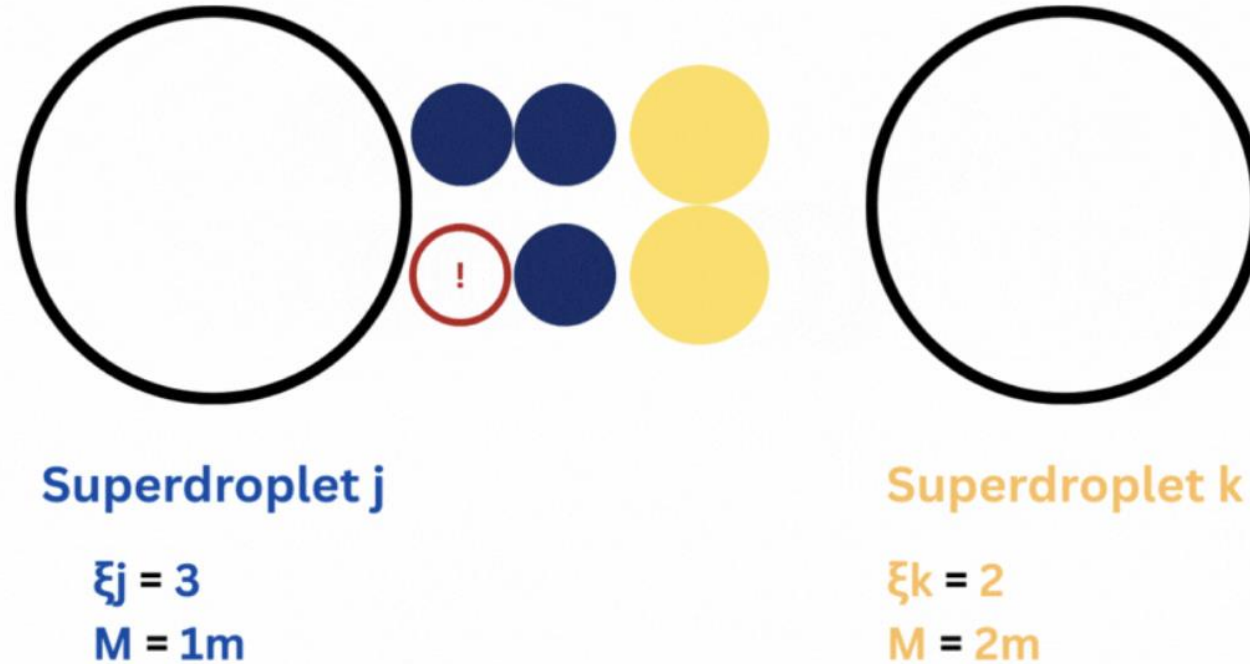


γ = integer number of events
predicted by probability
and Monte-Carlo success

- Faster than bin methods in high dimensional attribute space
- Scales efficiently with number of attributes and particles
- Embarrassingly Parallel
- No numerical diffusion (retains particle identity)
- Conserves mass and N_s

- Background on Cloud Processes
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Deficit Problem ($\gamma = 2, \xi_j < \gamma \xi_k$)



- Shima et al., 2009 limit γ by $\frac{\xi_k}{\xi_j}$
- Pointed out in Dziekan and Pawlowska (2017)
- Quantified in Bartman, P., & Arabas, S. (2023).

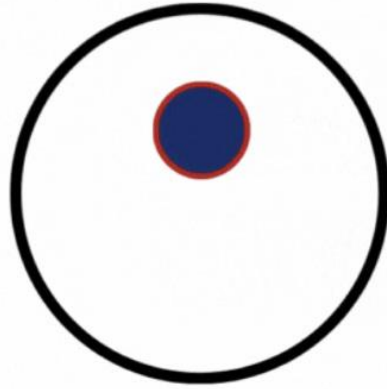
$$\gamma > \frac{\xi_j}{\xi_k} !!$$



$$\gamma_{occured} = \left\lfloor \frac{\xi_j}{\xi_k} \right\rfloor$$

$$\gamma_{occured} < \gamma_{predicted}$$

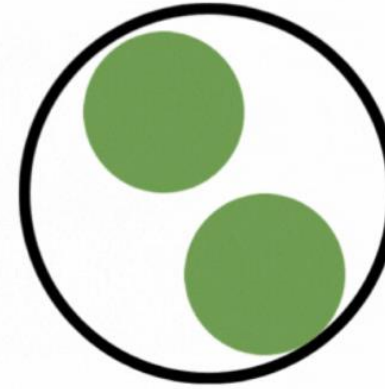
Deficit Problem ($\gamma = 2, \xi_j < \gamma \xi_k$)



Superdroplet j

$$\xi_j = 3 - \xi_j / \xi_k = 1$$

$$M = 1m$$



Superdroplet k

$$\xi_k = 2$$

$$M = 2m + 1m = 3m$$

$$\gamma > \frac{\xi_j}{\xi_k} !!$$



$$\gamma_{occured} = \left\lfloor \frac{\xi_j}{\xi_k} \right\rfloor$$

$$\gamma_{occured} < \gamma_{predicted}$$

- Shima et al., 2009 limit γ by $\frac{\xi_k}{\xi_j}$
- Pointed out in Dziekan and Pawlowska (2017)
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$$deficit = (\gamma_{predicted} - \gamma_{occured}) \cdot \xi_k$$

Adaptive Time-Stepping Algorithm

$$deficit = (\gamma_{predicted} - \gamma_{occured}) \cdot \xi_k \quad p_{pair\,j,k} = \frac{timestep}{collision\,volume} \cdot \xi_j \cdot \frac{total\,pairs}{pairs\,tested} \cdot Kernel(j,k),$$

We want to avoid $\gamma_{predicted} > \left\lfloor \frac{\xi_j}{\xi_k} \right\rfloor$:

Find the maximum timestep allowed for the pair:

$$p_{pair\,j,k} = \tilde{p}_{pair} \Delta t$$

$$\Delta t_{max\,pair} = \left\lfloor \frac{\xi_j}{\xi_k} \right\rfloor / \tilde{p}_{pair}$$

Find the limiting timestep for the cell:

$$\Delta t_{adaptive} = \min(\{\Delta t_{max\,pair} \dots\}, \Delta t_{parent})$$

Repeat the substep until the model step is complete:

$$\Delta t_{left} = \Delta t_{parent} - \Delta t_{adaptive}$$

Adaptive Time-Stepping Analogies

If an algorithm does not have a way to handle multiple collisions, it must have an analogous method to constrain the probability < 1

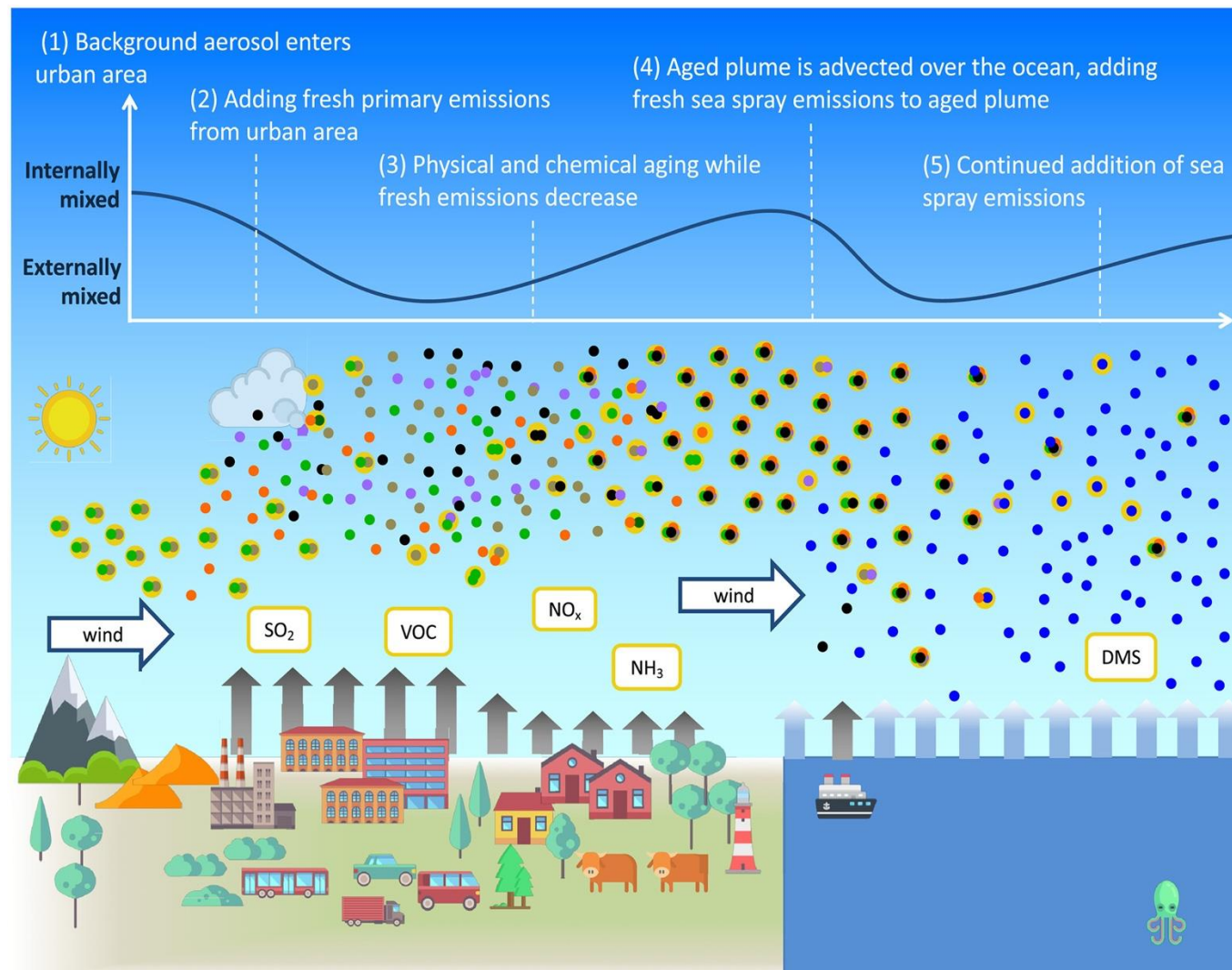
RemappingAlgorithm(RMA), Andrejczuk et al. (2010)

- RMA remaps between Superdroplets and binned mass every coalescence step
- Unterstrasser et al. (2017) proposes an adaptive substep when limited by bin concentration
- Comments on the stiffness of the Hall kernel when there are large droplets

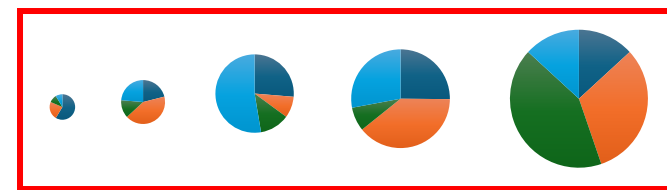
Weighted Flow Algorithm (WFA), Deville et al. (2011)

- used in PartMC (West, Riemer, et al., 2022)
- Particle-based Monte-Carlo algorithm
- Weighting is not a particle attribute
- optimizes the number of pairs tested out of the possible pairs

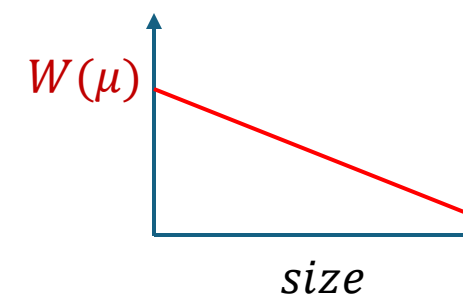
Adaptive Time-Stepping Analogies: WFA



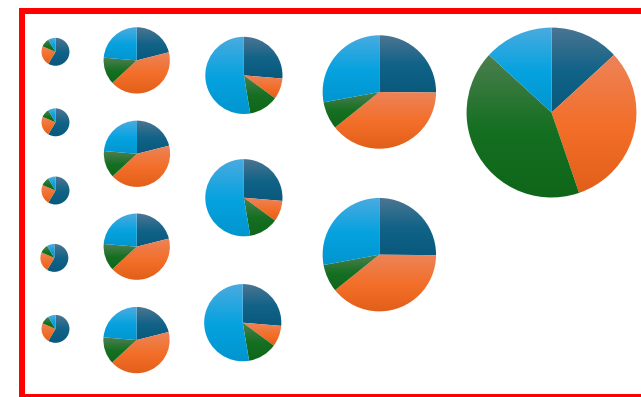
superparticle population:



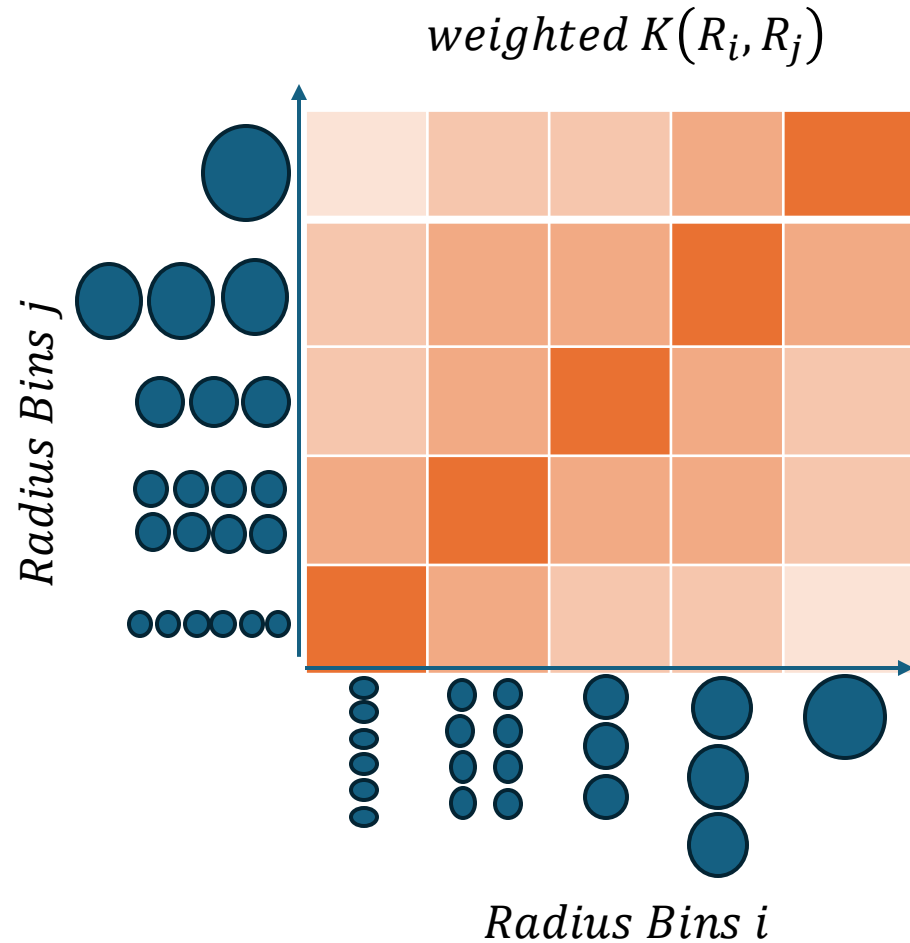
weighting function:



particle population:



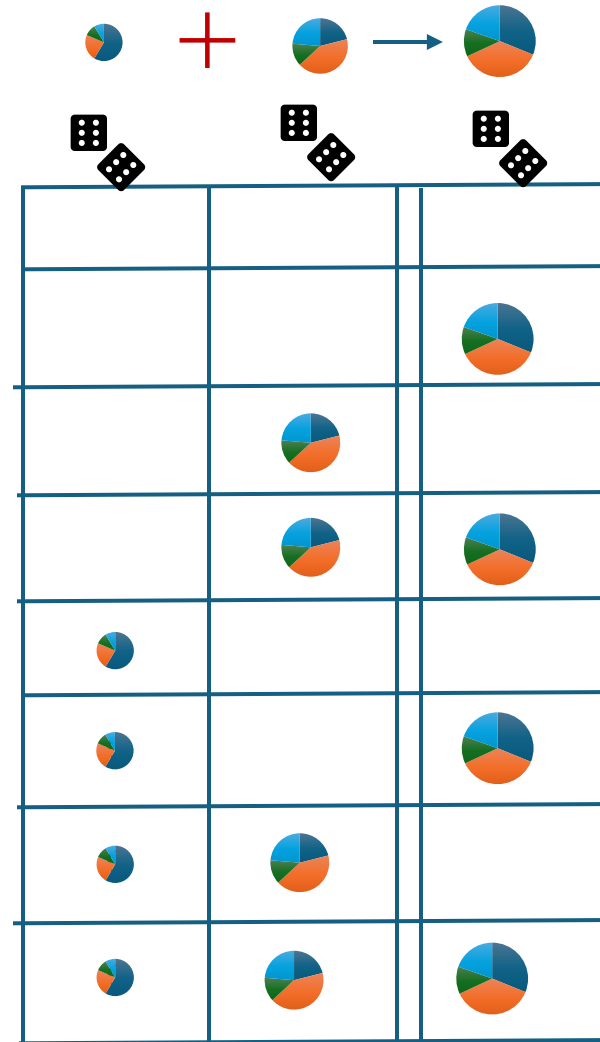
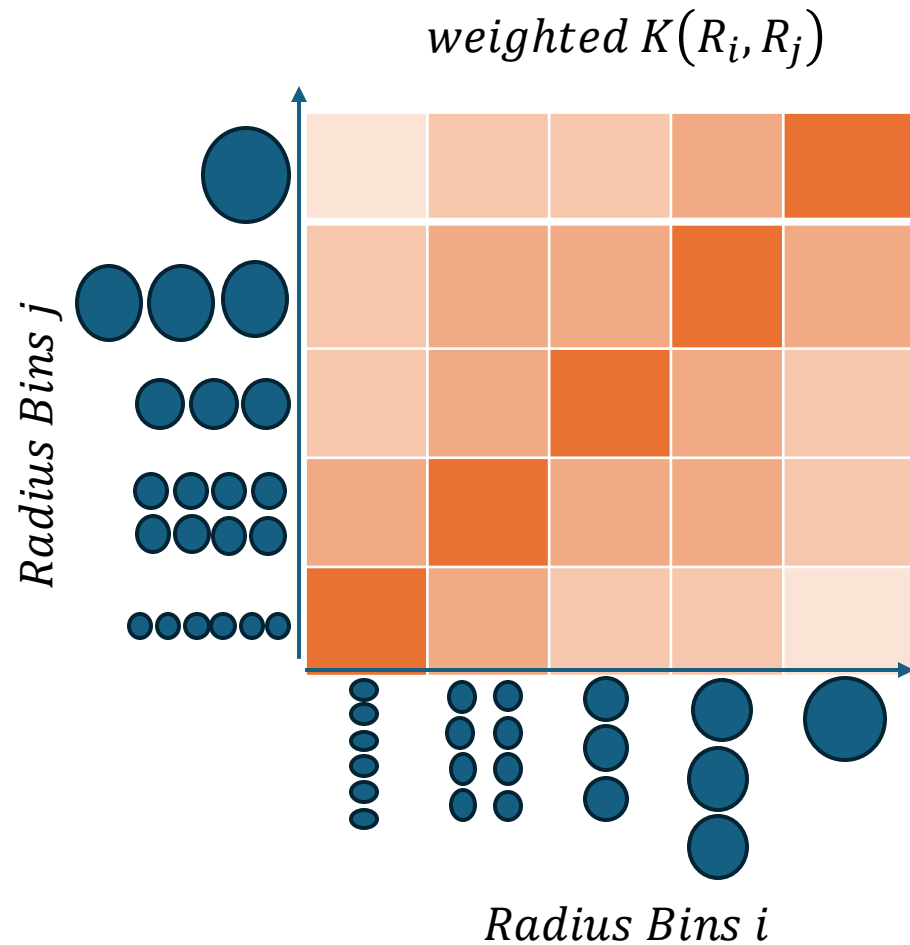
Adaptive Time-Stepping Analogies: WFA



$$p_{\alpha} \propto \frac{\text{total pairs in bin}_{ij}}{\text{pairs tested}} \cdot \text{weighted Kernel}(R_i, R_j)$$

- Weighted Kernel of bin pair does not change in time
- Pairs tested is optimized at coarse bins by maximizing p_{α} to 1

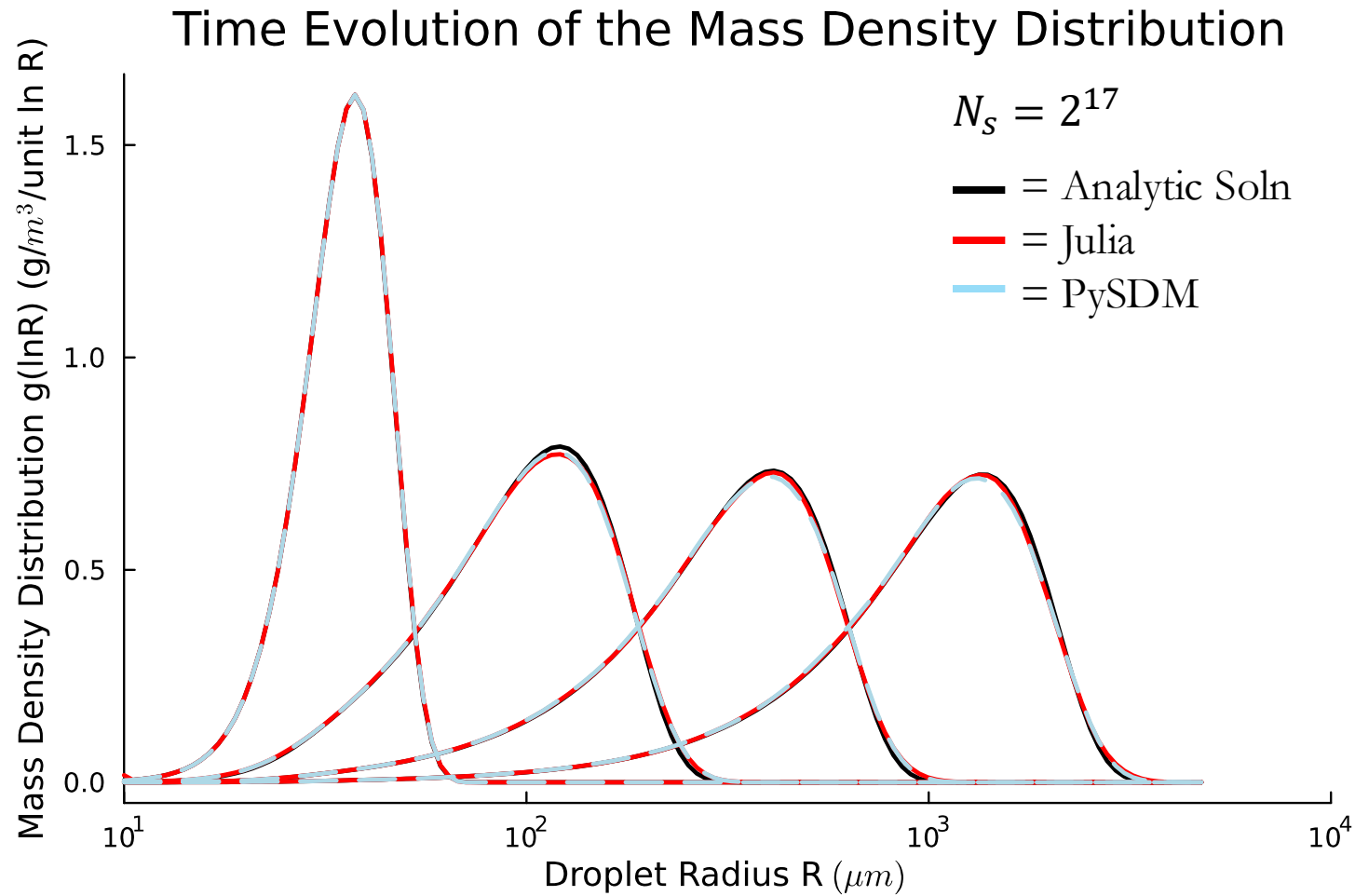
Adaptive Time-Stepping Analogies: WFA



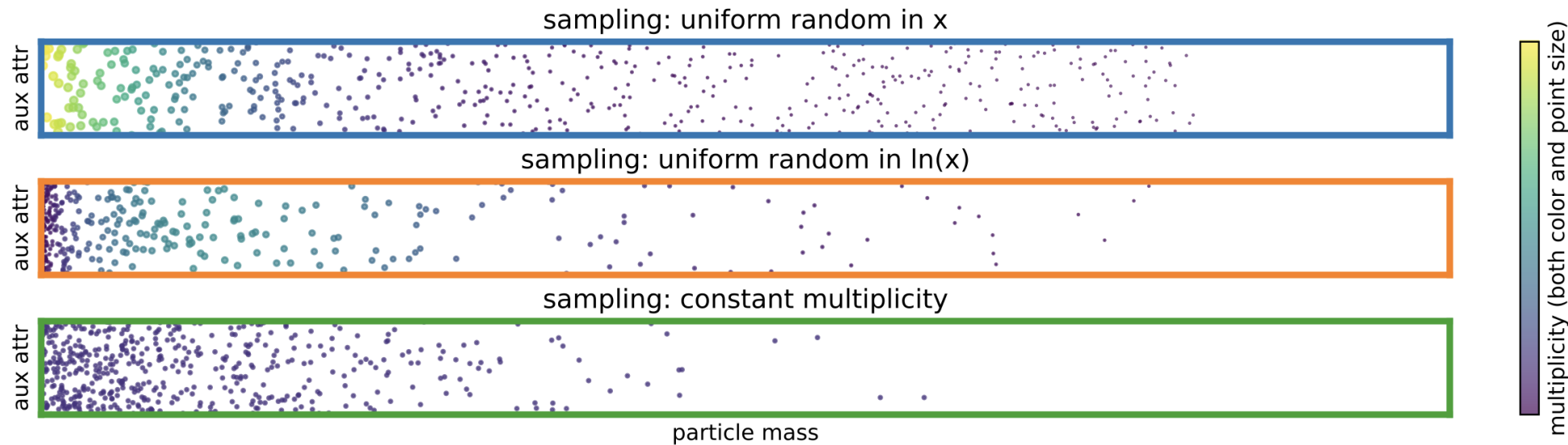
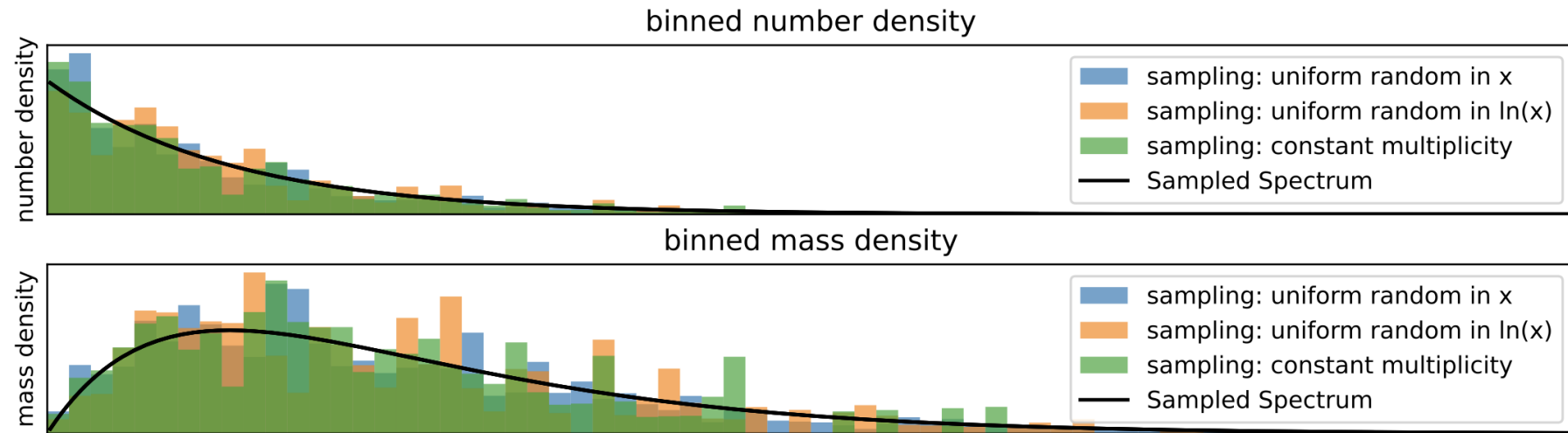
- Weights are helpful for the optimization
- Resulting superparticle might not be the weight of adding two smaller superparticles
- All 3 are probability checked for existence after a collision event based on their weights

- Background on Cloud Processes
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- **Adaptivity in a Box model**
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Box Model Test Setup

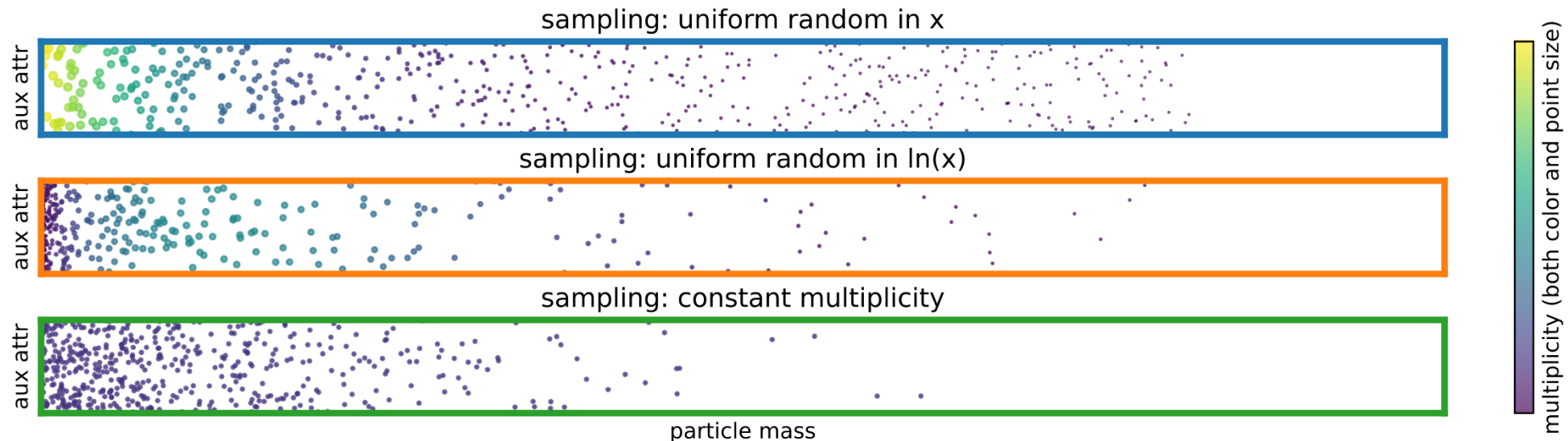


Initialization



Initialization

- Optimization and comparison of initialization is explored in Unterstrasser et al. 2017 and 2019, Dziekan and Pawlowska 2017, Matsushima et al. 2023)
- Initializations with dynamic ranges of multiplicities are shown to do best
- Matsushima et al. (2023) proposed a new init method that parameterizes this dynamic spread

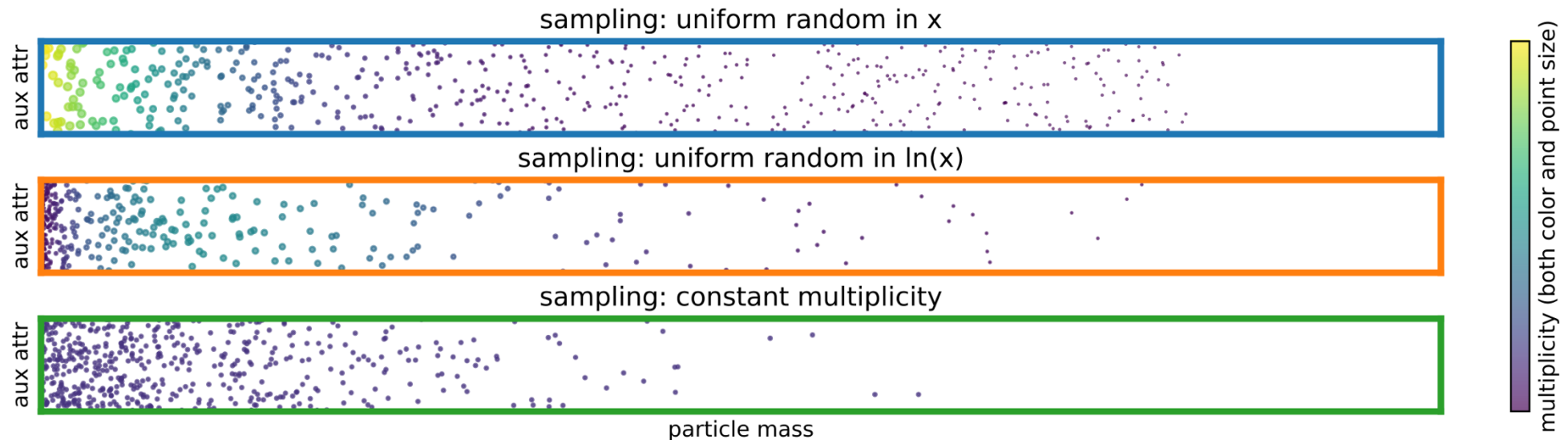


Initialization

$$p_{\text{superdroplet pair}} = \xi_j \cdot p_{\text{droplet pair}}, \quad \uparrow \quad \text{choose } \xi_j > \xi_k$$

$$\text{droplet collisions per event} = \xi_j \cdot \xi_k \cdot p_{\text{droplet pair}} \quad \downarrow \quad \text{Dynamic range}$$

It is advantageous to have many superdroplet events of small multiplicities ξ_k

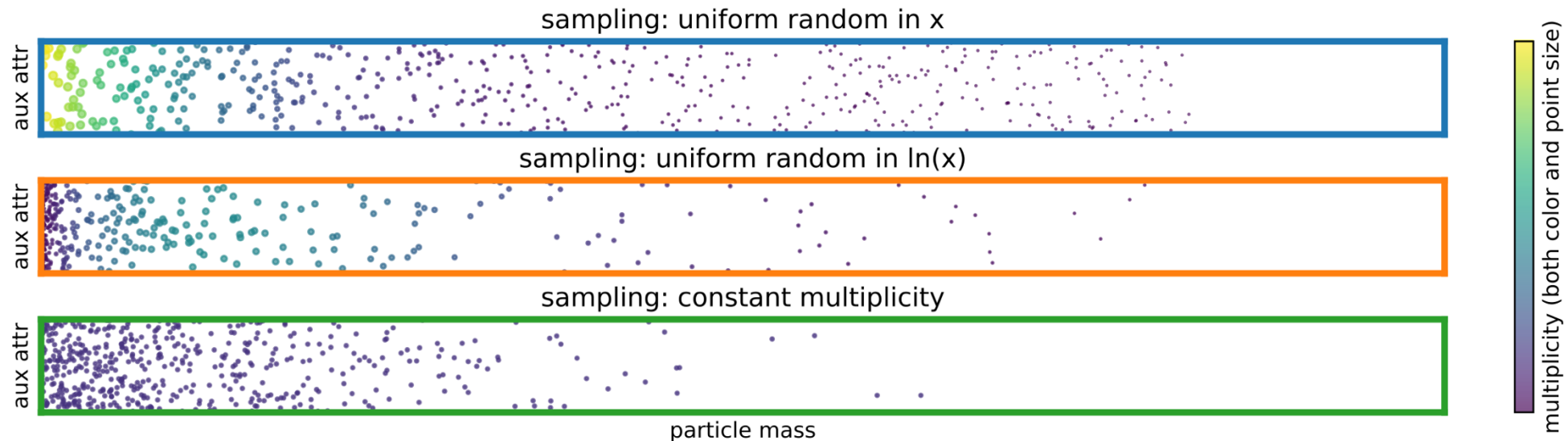


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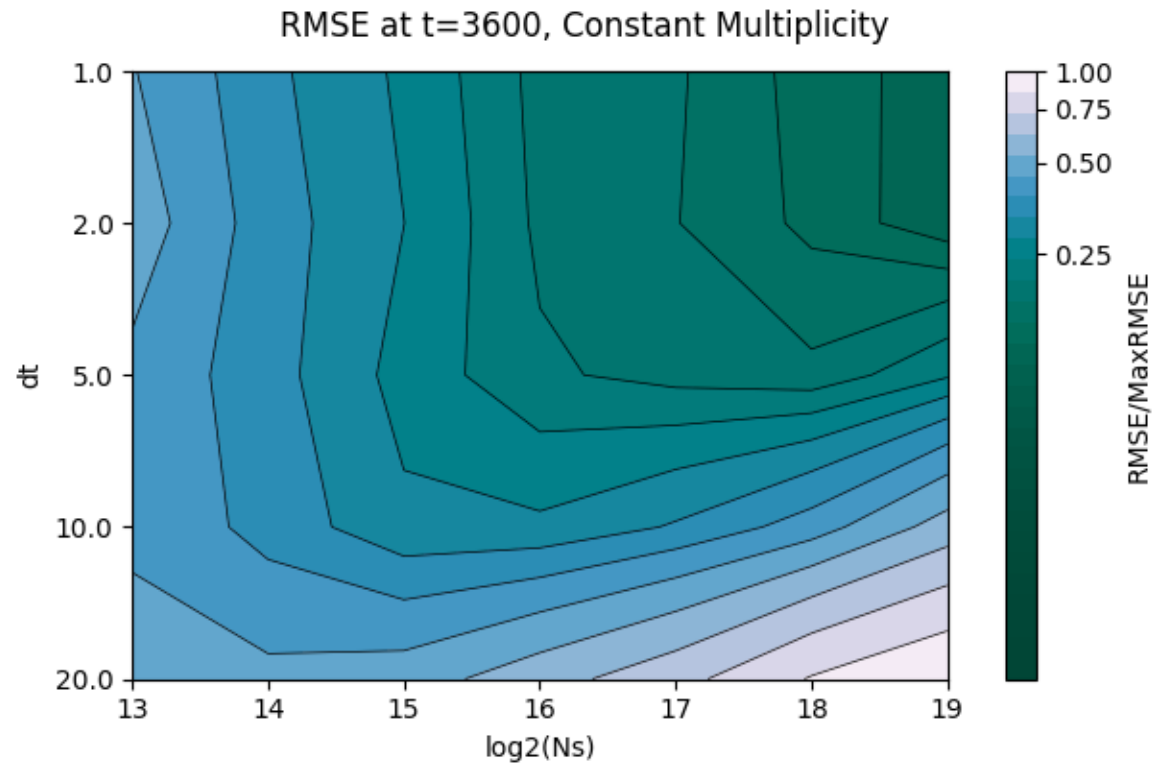
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Lucky for deficit, dynamic range also maximizes $\overline{\xi_j / \xi_k}$

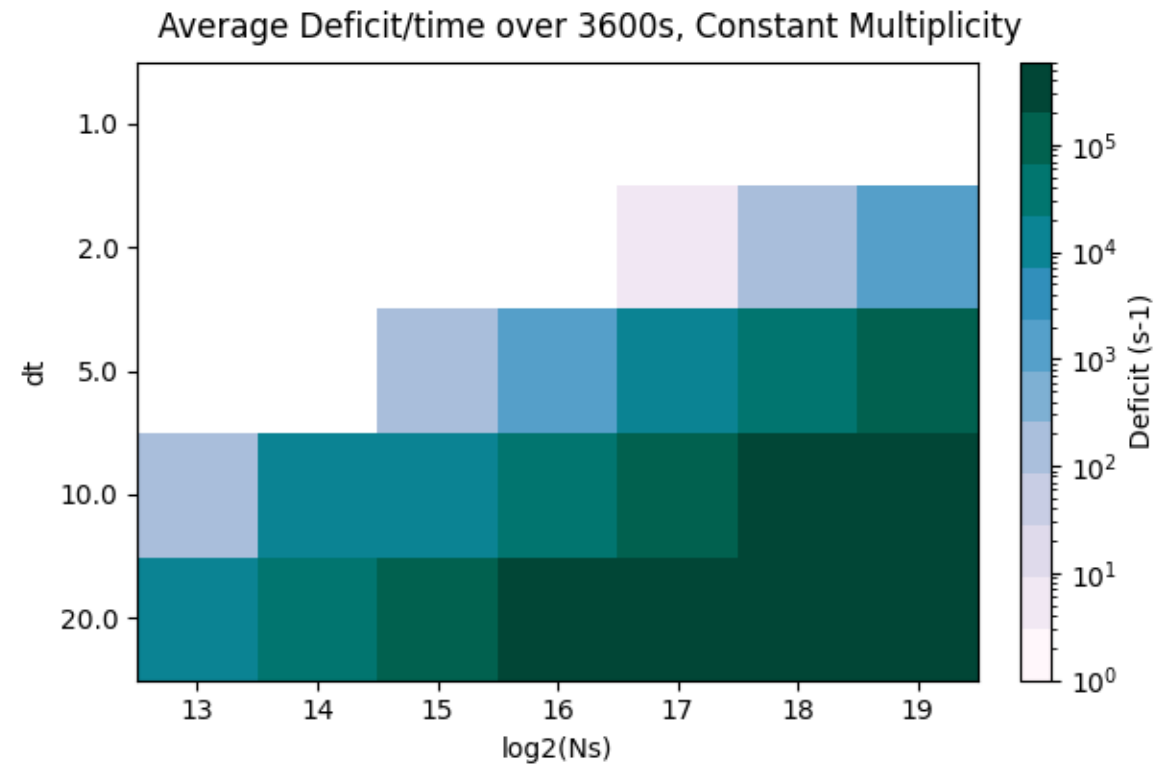
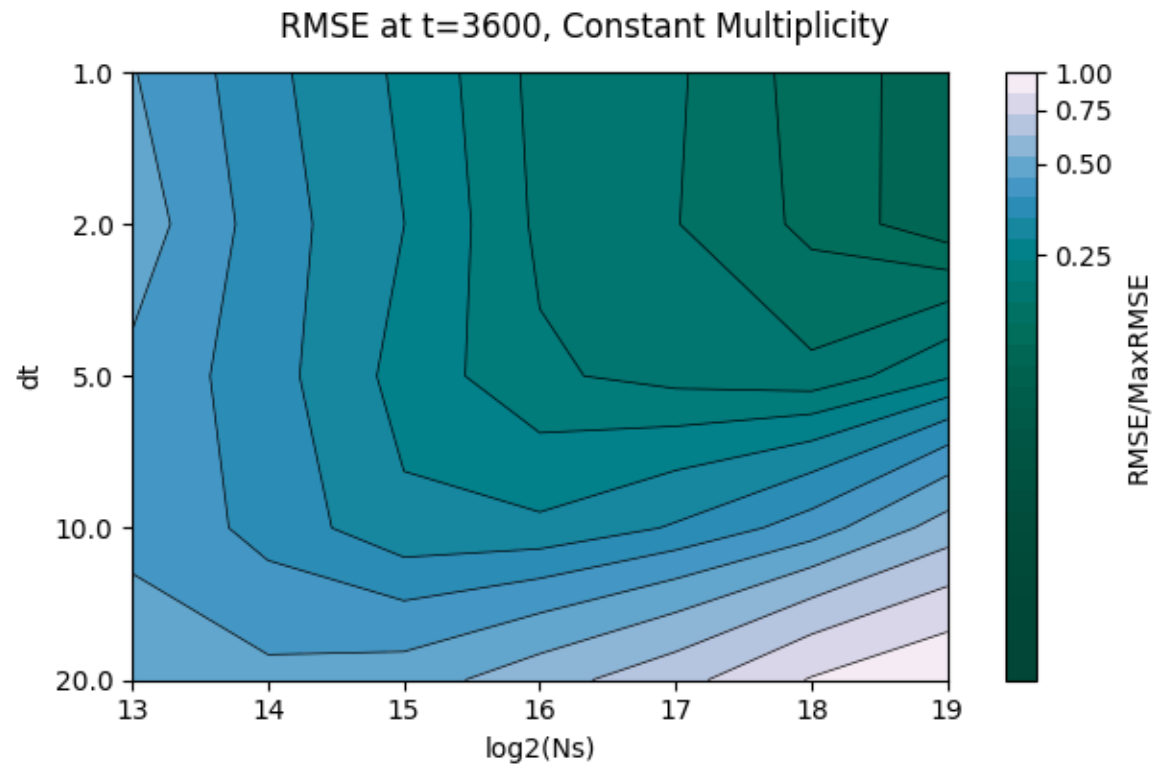


SDM Adaptivity in a Box Model

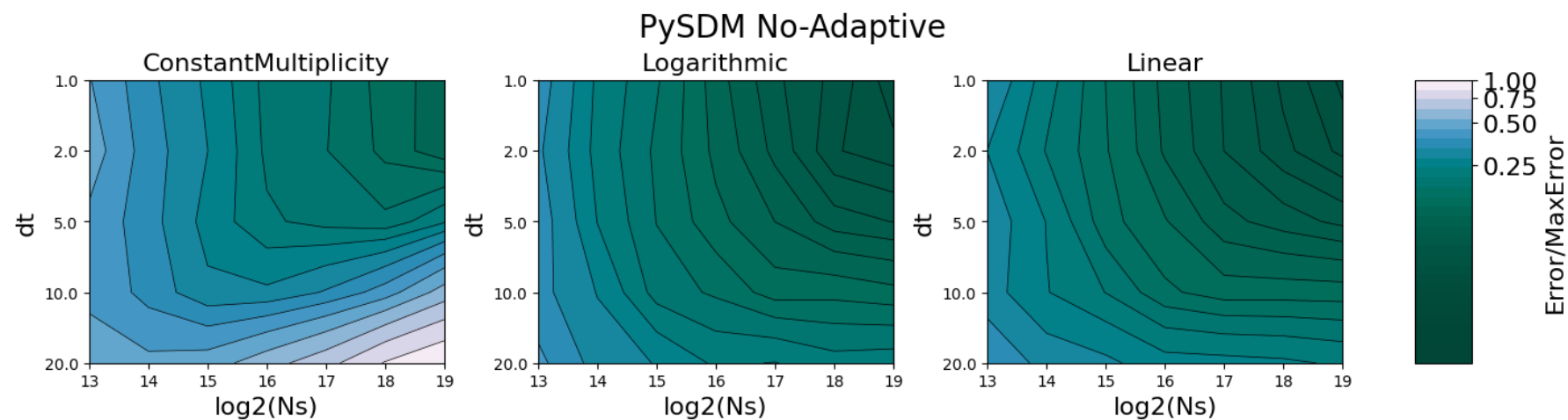


- 15 runs
- Increasing error with more superdroplets??

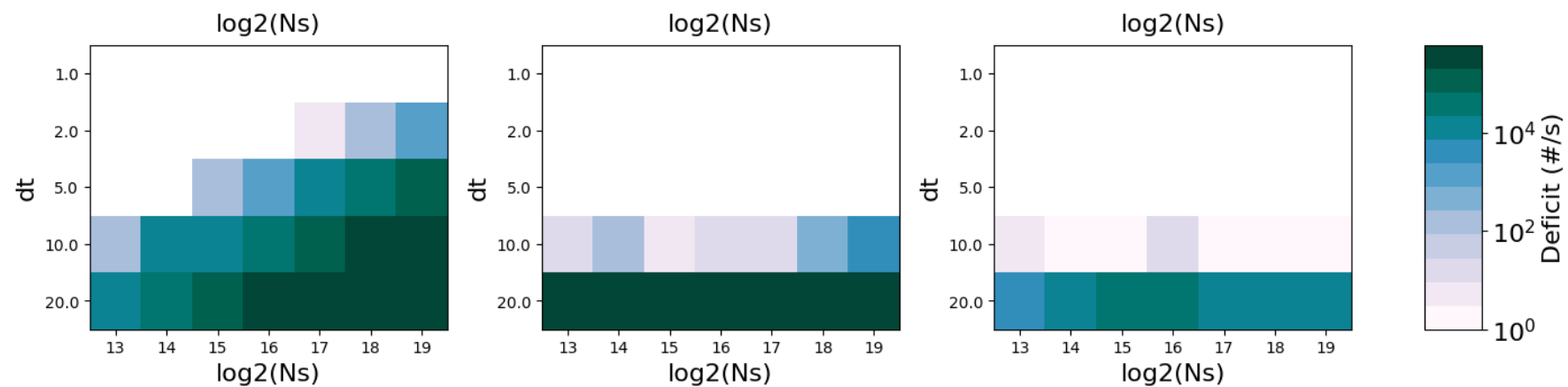
SDM Adaptivity in a Box Model

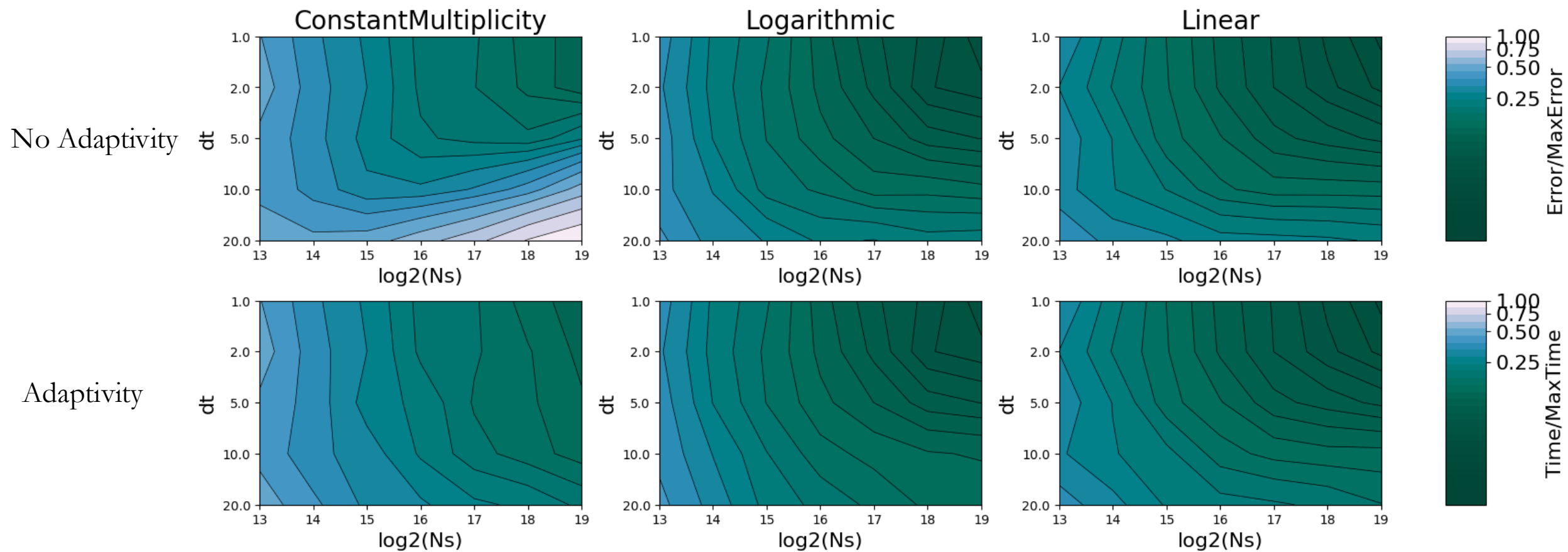


(RMSE $t = 3600s$)
 Fraction of largest error



Deficit (#/s)

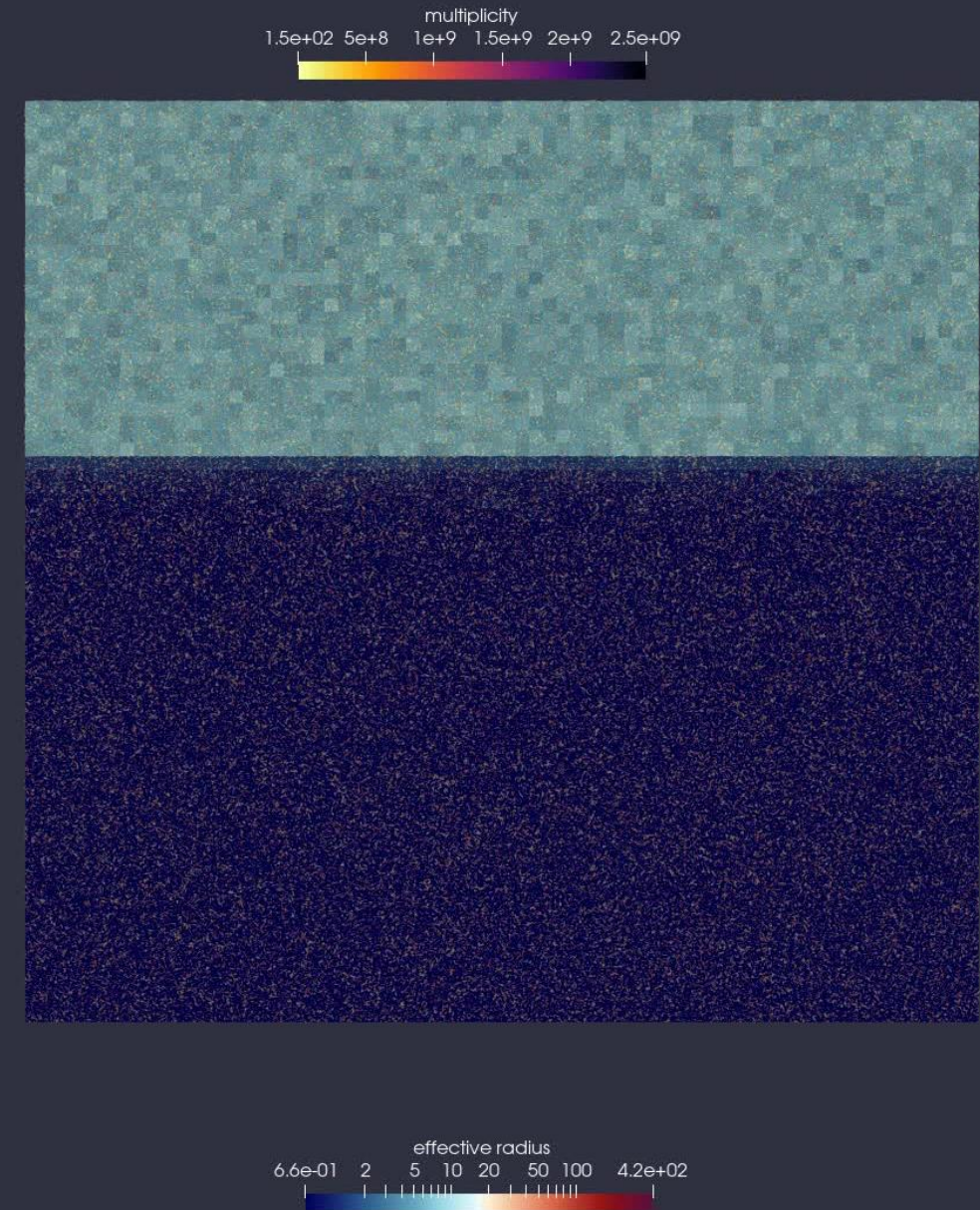




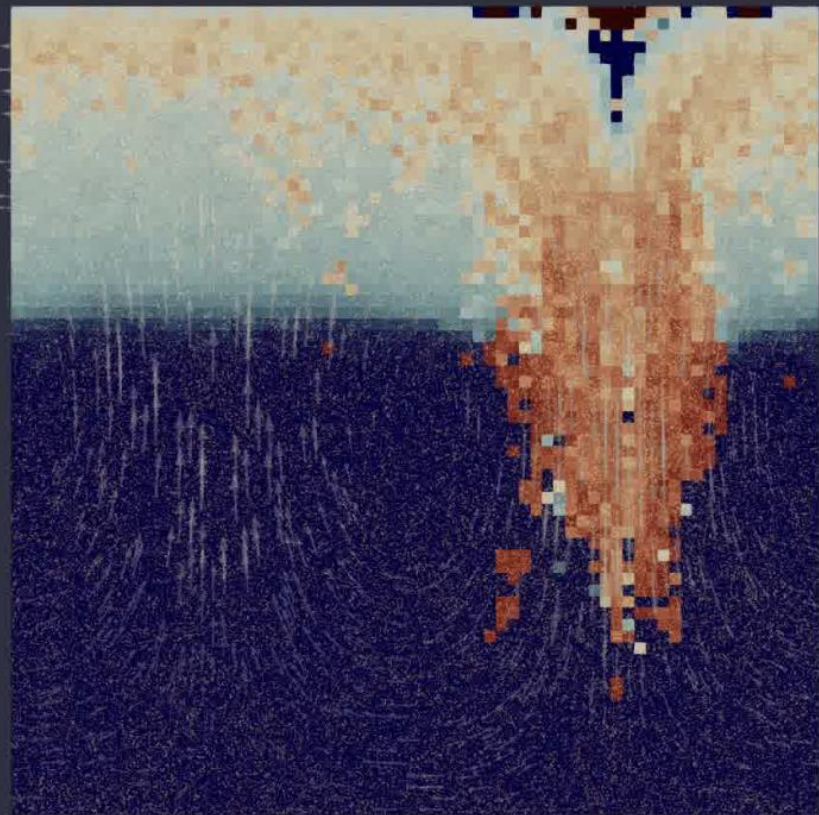
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2D prescribed velocity field

- Kessler 1969 Kinematic framework
- How does it behave with flow, grid exchange
- Unterstrasser et al. (2019) show less SD needed for 1d convergence
- 35 runs
- The results here only show varying time step
- 1.5x1.5 km domain, 50x50 grid, 40SD/cell
- Initialized by Uniform Log(dry radius)
- Geometric Kernel



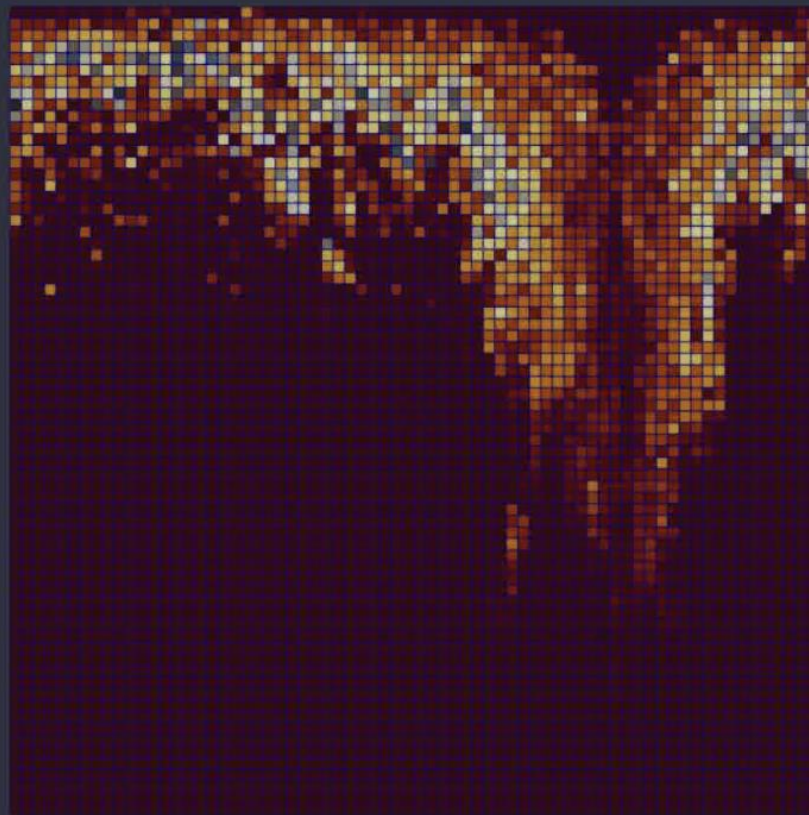
multiplicity
1.5e+02 1e+9 2.5e+09



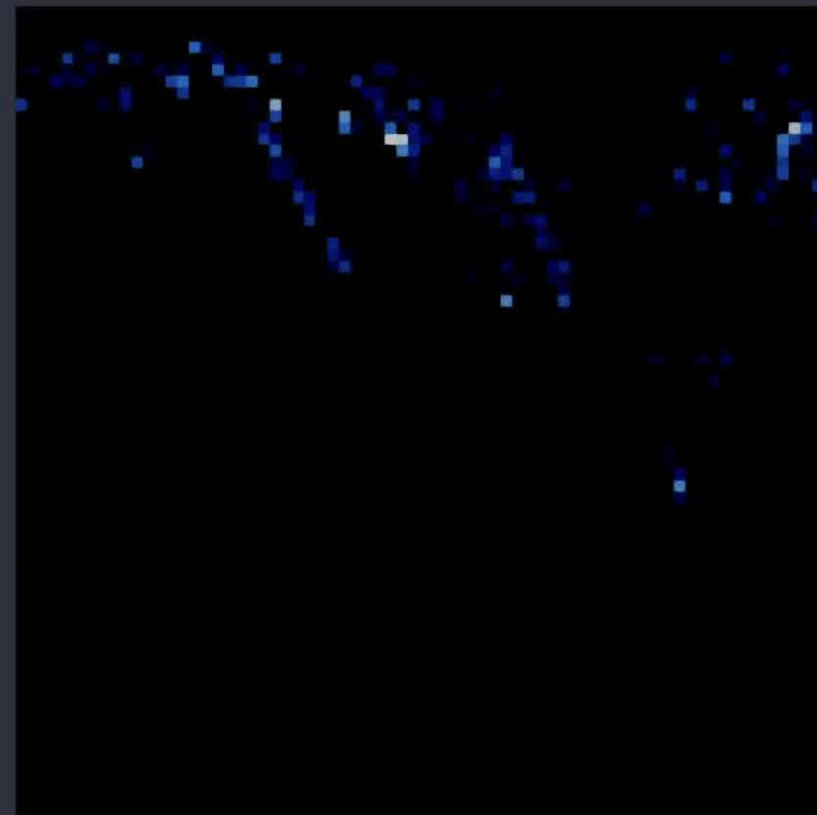
effective radius (um)
6.6e-01 2 5 10 20 50 100 3.2e+02



Time: 4920.000000



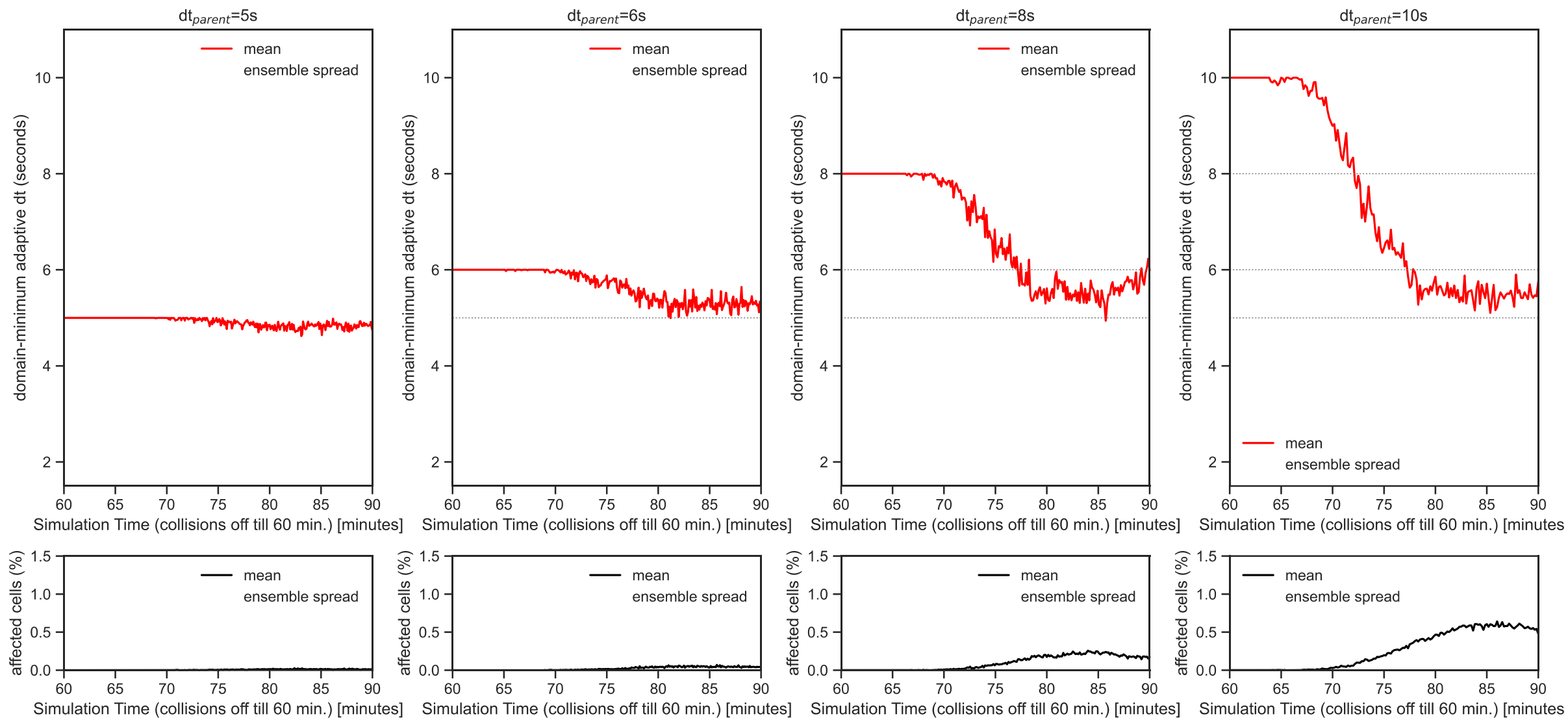
collision rate (s-1)
0.0e+00 200000 3.8e+05



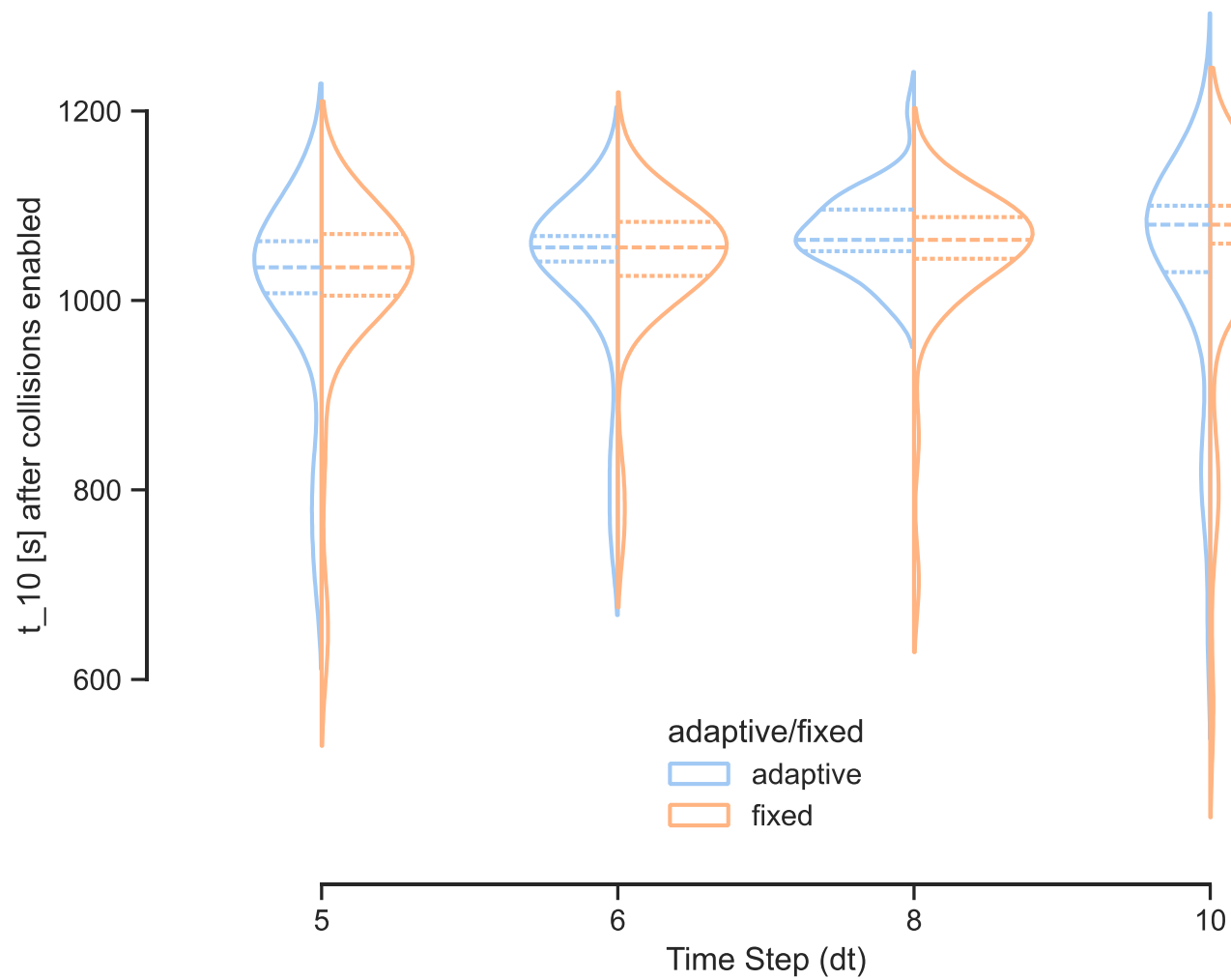
collision timestep minimum (s)
3.1e+00 5 1.0e+01



35 runs, adaptivity on (zero deficit), grid=50x50, init $n_{sd} \approx 40/\text{cell}$



Time to 10% of cloud mass as rain (>40 μ m), 35 runs



- Given these conditions, we do not see increased convergence of bulk properties with adaptive time stepping

Despite Low Effect on the Convergence
shown here, we *still recommend implementation*

$$p_{\alpha} \propto \frac{\Delta t}{\Delta V} \cdot \xi_J \cdot \frac{(N_{SD}-1)N_{SD}}{N_{SD}} \cdot K(R_i, R_j), \quad \bar{\xi}_J \propto f(\text{init}) \cdot \left(\frac{n_{\text{cell droplets}} \cdot \Delta V}{N_{SD}} \right)$$

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$$\bar{p}_{\alpha} \propto \Delta t \cdot f(init) \cdot n_{cell} \cdot K(R_i, R_j)$$

Despite Low Effect on the Convergence shown here, we *still recommend implementation*

- The setups used might not indicate any urgent need to reduce the deficit, but embracing the adaptivity makes the scheme more robust and less sensitive to arbitrary user settings
- Easily quantified nonphysical error that only lowers the growth
- Only affecting a small fraction of the grid cells ($<1\%$) – not a reason to lower timestep
- This is not a domain wide setting: extra computational effort is focused where needed
- Increased superdroplet resolution does not reduce deficit

In summary...

- Sensitivity to deficit is much smaller than convergence on init methods/#sd
- Dynamic multiplicity range helps convergence *and* deficit while increasing Nsd does not
- PySDM and Droplets.jl are open source
- Ware, Bartman et al. (in prep.)

